

Inductive Logic Programming for Interactive Theorem Proving

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Motivation

- AITP has many challenges:
 - bad at incremental learning
 - poor explainability
 - very large action space
 - bad at planning
 - low accuracy
 - ...
- Only statistical ML is applied for TP.
- I feel statistical ML is not enough for TP.
- Could we combine a very different ML technique called inductive logic programming (ILP) with statistical ML to develop stronger ML for TP?
- Use ILP to predict tactics for Coq.

ILP

- A subfield of symbolic artificial intelligence
- Goal: induce hypotheses that generalize training examples with background knowledge.
- Represented by first- or higher-order logic

Background Knowledge

mathematician(alice), mathematician(bob),
artist(clark), artist(david),
use_itp(alice), use_itp(clark), use_itp(david)

Positive Example

happy(alice)

Negative Examples

happy(bob), happy(clark),
happy(david)

- Hypothesis: $\text{happy}(X) \text{ :- mathematician}(X), \text{ use_itp}(X)$
- Interpretation: forall X , if X is a mathematician and uses ITP, he is happy.

Aleph

Background Knowledge

mathematician(alice), mathematician(bob),
artist(clark), artist(david),
use_itp(alice), use_itp(clark), use_itp(david)

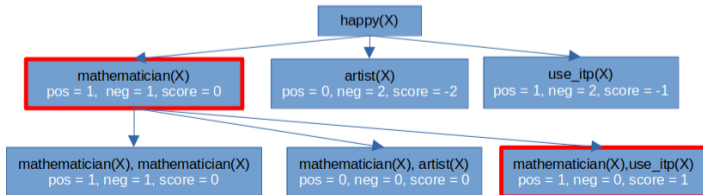
Positive Example

happy(alice)

Negative Examples

happy(bob), happy(clark),
happy(david)

- Arguably the most influential ILP system
- With appropriate parameters, we make Aleph roughly work as below.
- $\text{score} = \text{pos} - \text{neg}$



Encoding 1

```
n : nat
i : nat
H : i < n
H0 :  $\forall n : \text{nat}, \text{fact } (S\ n) = S\ n * \text{fact } n$ 
H1 :  $n - i = S\ (n - S\ i)$ 
-----
i < n
```

- Every node in the abstract syntax tree (AST) is converted to a fact.
- The encoding of the goal:
`coq_Init_Peano_lt(57, [0]). goal_coq_var(57, "i", [0,0]).`
`goal_coq_var(57, "n", [0,1]).`
- 57: the id of the proof state
- [0, 1]: the position of the node in the AST
- i: the name of the hypothesis that the node refers to

Encoding 2

```
n : nat
i : nat
H : i < n
H0 :  $\forall n : \text{nat}, \text{fact } (S\ n) = S\ n * \text{fact } n$ 
H1 :  $n - i = S\ (n - S\ i)$ 
-----
i < n
```

- The encoding of H:
`coq_Init_Peano_lt(57, "coq_H", ["coq_H", hyp_ass, 0]).`
`hyp_coq_var(57, "i", "coq_H", ["coq_H", hyp_ass, 0, 0]).`
`hyp_coq_var(57, "n", "coq_H", ["coq_H", hyp_ass, 0, 1]).`
- `coq_H`: the hypothesis that the node belongs to
- `["coq_H", hyp_ass, 0, 1]`: the position of the node in the hypothesis
- The texts "coq_H" and `hyp_ass` are used to distinguish the position of a hypothesis from the position of a goal.

Predicates

```
dif(HypName1, HypName2).
dif(HypPosition1, HypPosition2).
dif(GoalPosition1, GoalPosition2).
left(HypPosition1, HypPosition2).
left(GoalPosition1, GoalPosition2).
above(HypPosition1, HypPosition2).
above(GoalPosition1, GoalPosition2).
% Two subterms rooted at HypPosition1 and HypPosition2 are equal.
eq_subterm(ProofStateId, HypPosition1, HypPosition2).
eq_subterm(ProofStateId, GoalPosition1, GoalPosition2).
eq_subterm(ProofStateId, HypPosition, GoalPosition).
hyp_coq_var(ProofStateId, HypName, HypName, HypPosition).
goal_coq_var(ProofStateId, HypName, GoalPosition).
```

Example 1

```
n : nat
i : nat
H : i < n
H0 :  $\forall n : \text{nat}, \text{fact } (S\ n) = S\ n * \text{fact } n$ 
H1 :  $n - i = S\ (n - S\ i)$ 
-----
i < n
```

```
tac(A,"assumption") :-
  coq_Init_Peano_lt(A,B), coq_Init_Peano_lt(A,C,D), eq_subterm(A,B,D).
```


Example 2

```
H1 : i <= N
-----
y = y ^ 1
```

run simpl

```
H1 : i <= N
-----
y = y * 1
```

```
tac(A,"simpl") :-
  coq_Init_Peano_le(A,B,C), coq_Init_Datatypes_0(A,D),
  coq_Reals_Rpow_def_pow(A,E), position_above(E,D),
  coq_Init_Datatypes_S(A,F), position_above(F,D).
```

Example 3

- Sometimes we can learn complicated structures.
- But the structures may not correspond to the rules in Coq users' minds.
- Simplify the power of one to the multiplication of one.

```
x : R
y : R
n : nat
Hrecn : (x + y) ^ n = sum_f_R0
      (fun i : nat => C n i * x ^ i * y ^ (n - i)) n
-----
x + y = (x + y) ^ 1
```

```
tac(A,"simpl") :-
  coq_Init_Datatypes_0(A,B), coq_Reals_Rdefinitions_RbaseSymbolsImpl_Rplus(A,C),
  coq_Reals_Rpow_def_pow(A,D), position_above(D,C), coq_Init_Datatypes_S(A,E),
  coq_Reals_Rdefinitions_RbaseSymbolsImpl_Rplus(A,F), dif(F,C).
```

Compared to Statistical ML

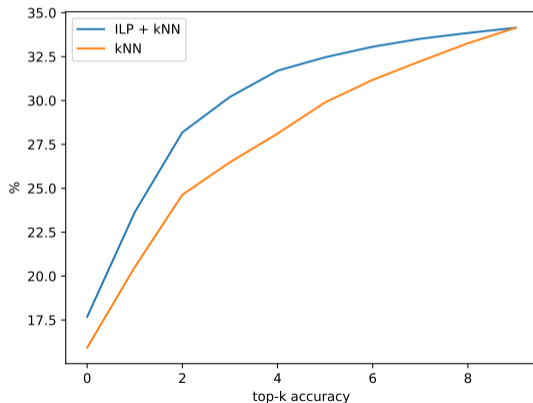
- ILP can represent relations:
 - horizontal relation and vertical relation
 - Features used in existing systems are only AST walks up to certain lengths.
 - equality
 - reference: a node and the hypothesis that it refers to
- ILP can characterize tactics.
- ILP is more explainable.

Connecting to Statistical ML

- The k -nearest neighbors classifier
 - The k -NN classifier ranks tactics by the distance measurement.
 - $jacard(f_1, f_2) = \frac{f_1 \cap f_2}{f_1 \cup f_2}$ where f_i is a set of features
- Train ILP
 - tactic t
 - positive examples: proof states applied with t .
 - negative examples: proof states that are not applied with t .
 - Use ILP to generate many rules for each tactic.
- Testing
 - Use k -NN to predict 10 tactics t_1, \dots, t_{10} for a proof state.
 - $\forall t_i$, if t_i does not satisfy any rule generated by ILP, add it to *bad*.
 - Else, add it to *good*.
 - Return *good* + *bad*

Results

- Train k -NN and ILP in 10% data from the Coq standard library.
- Test the performance in another 10%.



The End