

# Learning SMT Enumeration

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Aussois

## Background

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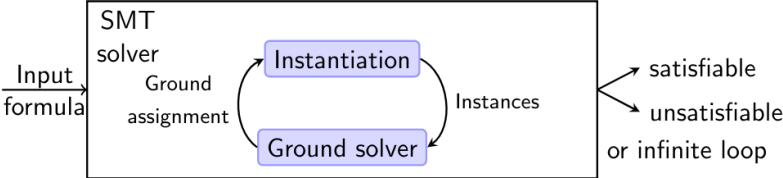
$$x \mapsto 0$$

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Then ground formula  $f(0) > 0 \wedge f(0) < 0$  cannot be satisfied.

# Background

Schematic of the SMT solver working with quantifiers:



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- Herbrand's theorem guarantees that for an unsatisfiable first-order logic formula, finitely many instantiations are sufficient to obtain an unsatisfiable ground part, and, these instantiations only need to use the Herbrand universe.
- A stronger variant of Herbrand's theorem that enables a more practical method for quantifier instantiation. It is sufficient to consider only the terms already within the ground part of the formula generated so far.
- This insight leads to the *enumerative instantiation* strategy.
- For a formula  $G \wedge \forall x_1 \dots x_n \phi$ , with  $G$  ground, collect all ground terms  $\mathcal{T}$  in  $G$  and strengthen  $G$  by an instantiation of  $\phi$  by an  $n$ -tuple  $t_1, \dots, t_n$  with  $t_i \in \mathcal{T}$ ; repeat the process until  $G$  becomes unsatisfiable or until resources are exhausted. The tuples are enumerated systematically to guarantee fairness.

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Let's consider the following conjunctive set of formulas within the logic of uninterpreted functions and linear integer arithmetic (UFLIA).

$$\{f(d) > f(d + 2), c \leq 0 \vee \underbrace{\forall x f(x) < f(x + 1)}_q\}$$

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**additional ground terms**

$$\{d, d + 2, c, 0, f(d), f(d + 2)\}$$

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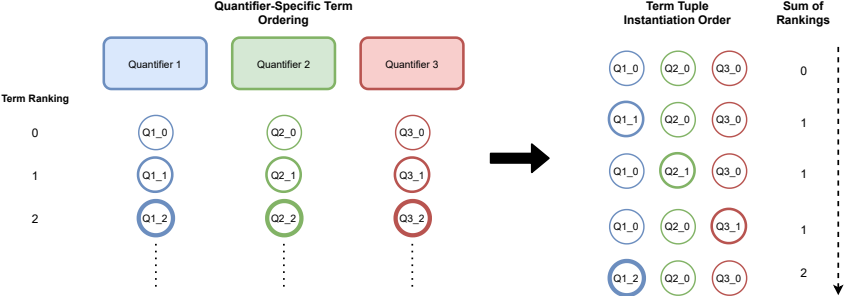
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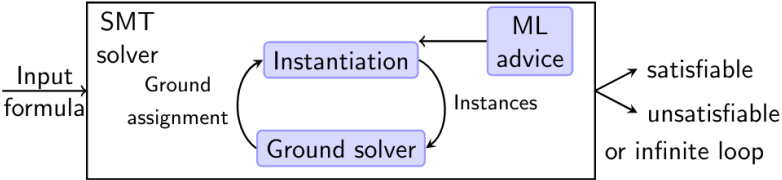
# Background



**Can machine learning make SMT solvers more efficient in the context of quantifiers?**

# Machine learning guidance

Schematic of the SMT solver with machine learning guidance for quantifier instantiation.



## Machine learning guidance

- Instead of ordering terms according to its age, we order them according to a scoring function  $S: \mathcal{F} \rightarrow [0, 1]$ .
- This function is parametrized as a machine-learning model – LightGBM.
- It takes as its argument the *features*  $F(\phi, t)$  of a pair of a quantified sub-formula  $\phi$  and the candidate term  $t$  which may be used for instantiation.
- It is trained on positive and negative examples:
  - $(\phi, t)$  is a positive if  $\phi$  instantiated with  $t$  appeared in a proof
  - $(\phi, t)$  is a negative if instantiating  $\phi$  with  $t$  was tried, but it did not appear in a proof.

# Features

- *bag-of-words* (BOW) features:
  - we use *kinds* of symbols determined by CVC5 (like: *variable*, *skolem*, *not*, *and*, *plus*, *forall*, and many others)
  - we count how many times a given kind of symbol appeared
  - for example:  $\text{BOW}(\forall x 2 + x = \text{skl}_1 + 3) =$   
 $\{\text{forall} : 1, \text{variable} : 1, \text{const} : 2, \text{skolem} : 1, \text{plus} : 2\}$
- additional features:
  - *varFrequency*
  - *age*
  - *phase*
  - *relevant*
  - *depth*
  - *tried*

Given an example  $(\phi, t)$ , its final feature representation is a vector

$$\text{BOW}(\phi) + \text{BOW}(t) + \text{additional features}$$



## Data for evaluation

Three SMT-LIB benchmarks:

- UFLIA Sledgehammer
- UFNIA Sledgehammer
- UFLIA Boogie

## Experimental setting

- One theorem may have multiple different proofs.
- One proof may result from multiple different proof-searches.
- This makes the notion of *positive / negative example* vague.

## Experimental setting

Having a set of SMT problems, one can have two similar – but not equivalent – goals, which are equally important:

1. the *cumulative goal*: solve automatically as many of the problems as possible, running the ML-guided solver multiple times over them and improving it by training the ML model on data collected across the runs,
2. the *generalization goal*: use the available problems to train a single ML-guided solver which performs well on new, unseen problems.

## Looping training and evaluation

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**Algorithm 1** Solving-training loop with training/testing split.

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**Require:** training problems:  $P_{\text{train}}$ , testing problems:  $P_{\text{test}}$ , number of iterations:  $N$ , grid of hyper-parameters:  $H_{\text{grid}}$

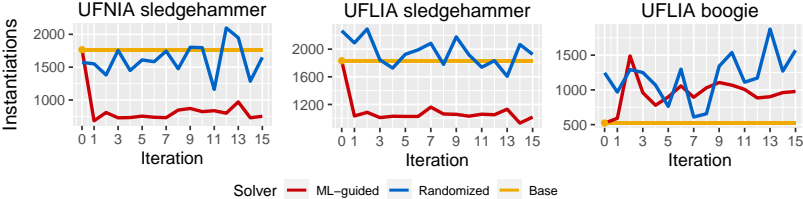
- 1:  $M \leftarrow \{\}$
  - 2:  $D_{\text{train}} \leftarrow \{\}$
  - 3: **for**  $i \leftarrow 0$  to  $N$  **do**
  - 4:      $L_{\text{train}} \leftarrow \text{SOLVE}(P_{\text{train}}, M)$
  - 5:      $L_{\text{test}} \leftarrow \text{SOLVE}(P_{\text{test}}, M)$
  - 6:      $D_{\text{train}} \leftarrow D_{\text{train}} \cup \text{EXTRACTTRAININGEXAMPLES}(L_{\text{train}})$
  - 7:      $H_{\text{best}} \leftarrow \text{GRIDSEARCH}(D_{\text{train}}, H_{\text{grid}})$
  - 8:      $M \leftarrow \text{TRAINMODEL}(D_{\text{train}}, H_{\text{best}})$
-

## 3 solvers compared in the experiments

1. **Base solver**: uses standard enumerative instantiation strategy
2. **Randomized solver**: like the base solver, but random 10% of terms are swapped
3. **ML-guided solver**: like the base solver, but terms are ordered according to ML-advice

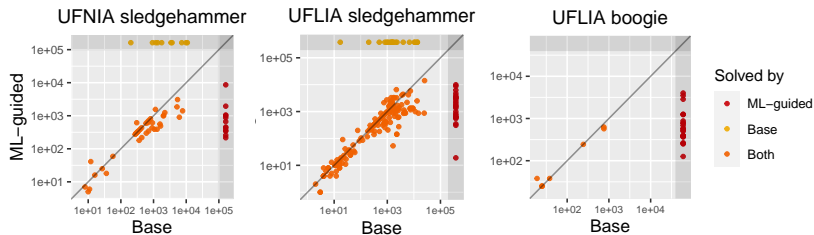
# Results

Instantiations made by the solvers for testing problems across iterations of the evaluation:



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Instantiations performed by the solvers  
(each point refers to one testing problem):







## Future work

- Finding more clever way of dealing with tuples of variables.
- Designing more informative features.

**Thank you!**