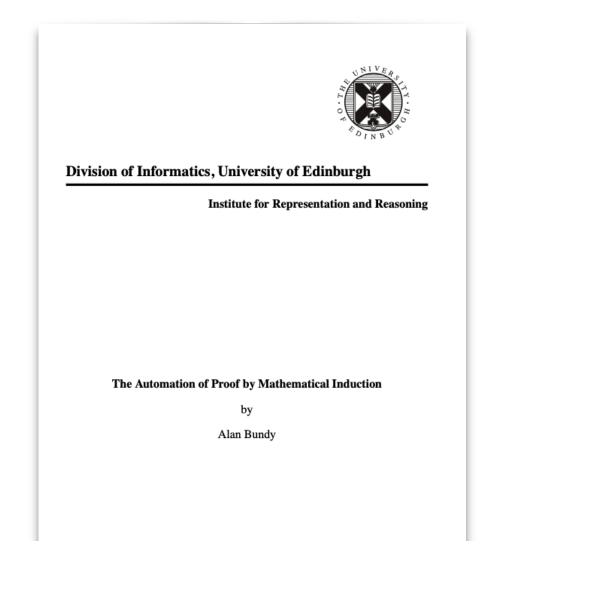
Automation of proof by induction in Isabelle/HOL using Domain-Specific Languages

LiFtEr: Logical Feature Extractor SeLFiE: Semantic Logical Feature Extractor

This work was supported by the project AI&Reasoning (reg. no. CZ.02.1.01/0.0/0.0/15_003/0000466).



Yutaka Nagashima, AITP, France, September 2020





Division of Informatics, University of Edinburgh

Institute for Representation and Reasoning

(Proof by induction) is thus a vital ingredient of formal methods for synthesising, verifying and transforming software and hardware. (1999)

The Automation of Proof by Mathematical Induction

by

Alan Bundy



Austintate https://en.wikipedia.org/wiki/Alan_Bundy#/media/File:Alan.Bundy.Image.jpg http://creativecommons.org/licenses/by-sa/3.0/



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[4]	German Research Center for Artificial Intelligence	ACOBS UNIVERSITY UNIVERSITY	
arXiv:1309.6226v5 [cs.AI] 28 Jul 2014	http://wirth.bplaced.net/seki.html ISSN 1437-4447		of formal methods for re and hardware. (1999)
6	http://wirth. ISSN 1437-4447		Austintate ja.org/wiki/Alan_Bundy#/media/File:Alan.Bundy.Image.jpg ://creativecommons.org/licenses/by-sa/3.0/

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Artificial Intelligence 62 (1993) 185-253 Elsevier 185

ARTINT 974

Rippling: a heuristic for guiding inductive proofs

Alan Bundy, Andrew Stevens*, Frank van Harmelen**, Andrew Ireland and Alan Smaill

Department of Artificial Intelligence, University of Edinburgh, 80 South Bridge, Edinburgh EH1 1HN, Scotland, UK

Received December 1991 Revised July 1992

Abstract

Bundy, A., A. Stevens, F. van Harmelen, A. Ireland and A. Smaill, Rippling: a heuristic for guiding inductive proofs, Artificial Intelligence 62 (1993) 185-253.

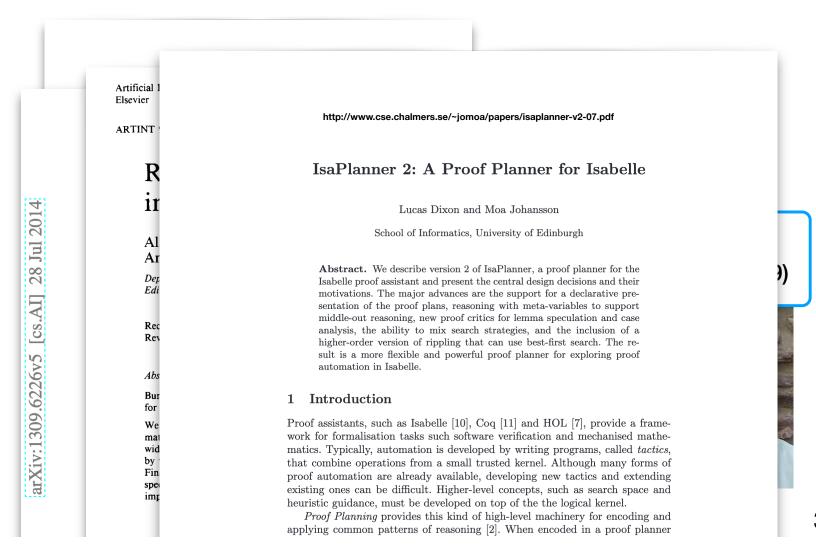
We describe rippling: a tactic for the heuristic control of the key part of proofs by mathematical induction. This tactic significantly reduces the search for a proof of a wide variety of inductive theorems. We first present a basic version of rippling, followed by various extensions which are necessary to capture larger classes of inductive proofs. Finally, we present a generalised form of rippling which embodies these extensions as special cases. We prove that generalised rippling always terminates, and we discuss the implementation of the tactic and its relation with other inductive proof search heuristics.

https://era.ed.ac.uk/bitstream/handle/1842/4748/BundyA_Rippling%20A%20Heuristic.pdf;sequence=1

formal methods for and hardware. (1999)



Austintate /wiki/Alan_Bundy#/media/File:Alan.Bundy.Image.jpg ativecommons.org/licenses/by-sa/3.0/



Artificial I Elsevier ARTINT Hipster: Integrating Theory Exploration in a **Proof Assistant** R Moa Johansson, Dan Rosén, Nicholas Smallbone, and Koen Claessen 2014 11 Department of Computer Science and Engineering, Chalmers University of Technology {jomoa,danr,nicsma,koen}@chalmers.se 4 201 Jul Al Abstract. This paper describes Hipster, a system integrating theory Ar exploration with the proof assistant Isabelle/HOL. Theory exploration May 28 is a technique for automatically discovering new interesting lemmas in Dep a given theory development. Hipster can be used in two main modes. The first is *exploratory mode*, used for automatically generating basic Edi 4 arXiv:1309.6226v5 [cs.AI] lemmas about a given set of datatypes and functions in a new theory development. The second is *proof mode*, used in a particular proof attempt, 1 trying to discover the missing lemmas which would allow the current Rec goal to be proved. Hipster's proof mode complements and boosts existing [cs.LO] Rev proof automation techniques that rely on automatically selecting existing lemmas, by inventing new lemmas that need induction to be proved. We show example uses of both modes. Abs 1 Introduction Bur arXiv:1405.3426v1 for The concept of theory exploration was first introduced by Buchberger 2. He argues that in contrast to automated theorem provers that focus on proving We one theorem at a time in isolation, mathematicians instead typically proceed mat by exploring entire theories, by conjecturing and proving layers of increasingly wid complex propositions. For each layer, appropriate proof methods are identified, by and previously proved lemmas may be used to prove later conjectures. When a Fin new concept (e.g. a new function) is introduced, we should prove a set of new spe conjectures which, ideally, "completely" relates the new with the old, after which imp other propositions in this layer can be proved easily by "routine" reasoning. Mathematical software should be designed to support this workflow. This is arguably the mode of use supported by many interactive proof assistants, such as Theorema 3 and Isabelle 17. However, they leave the generation of new

Artificial Elsevier ARTINT R 2014 11 \forall 201 Jul Al Ar May 28 Dep Edi [cs.AI] 4 -Rec [cs.L0] Rev arXiv:1309.6226v5 Abs Bur .3426v1 for We mat wid arXiv:1405 by Fin spe imp

https://doi.org/10.1007/978-3-319-63046-5_32

A Proof Strategy Language and Proof Script Generation for Isabelle/HOL

Yutaka Nagashima and Ramana Kumar

Data61, CSIRO / UNSW

Abstract. We introduce a language, PSL, designed to capture high level proof strategies in Isabelle/HOL. Given a strategy and a proof obligation, PSL's runtime system generates and combines various tactics to explore a large search space with low memory usage. Upon success, PSL generates an efficient proof script, which bypasses a large part of the proof search. We also present PSL's monadic interpreter to show that the underlying idea of PSL is transferable to other ITPs.

1 Introduction

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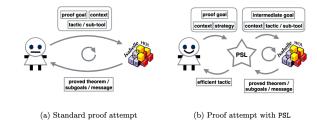
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[cs.LO]

arXiv:1606.02941v9

Currently, users of interactive theorem provers (ITPs) spend too much time iteratively interacting with their ITP to manually specialise and combine tactics as depicted in Fig. [13] This time consuming process requires expertise in the ITP, making ITPs more esoteric than they should be. The integration of powerful automated theorem provers (ATPs) into ITPs ameliorates this problem significantly; however, the exclusive reliance on general purpose ATPs makes it hard to exploit users' domain specific knowledge, leading to combinatorial explosion even for conceptually straight-forward conjectures.

To address this problem, we introduce PSL, a programmable, extensible, meta-tool based framework, to Isabelle/HOL [21]. We provide PSL (available on GitHub [17]) as a language, so that its users can encode *proof strategies*, abstract





https://www.logic.at/staff/gramlich/



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Electronic Notes in Theoretical Computer Science

IER Electronic Notes in Theoretical Computer Science 125 (2005) 5–43

5–43 _________ www.elsevier.com/locate/entcs

Strategic Issues, Problems and Challenges in Inductive Theorem Proving

Bernhard Gramlich¹

Fakultät für Informatik, TU Wien Favoritenstr. 9 – E185/2, A–1040 Wien, Austria

Abstract

(Automated) Inductive Theorem Proving (ITP) is a challenging field in automated reasoning and theorem proving. Typically, (Automated) Theorem Proving (TP) refers to methods, techniques and tools for automatically proving general (most often first-order) theorems. Nowadays, the field of TP has reached a certain degree of maturity and powerful TP systems are widely available and used. The situation with ITP is strikingly different, in the sense that proving inductive theorems in an essentially automatic way still is a very challenging task, even for the most advanced existing ITP systems. Both in general TP and in ITP, strategies for guiding the proof search process are of fundamental importance, in automated as well as in interactive or mixed settings. In the paper we will analyze and discuss the most important strategic and proof search issues in ITP, compare ITP with TP, and argue why ITP is in a sense much more challenging. More generally, we will systematically isolate, investigate and classify the main problems and challenges in ITP w.r.t. automation, on different levels and from different points of views. Finally, based on this analysis we will present some theses about the state of the art in the field, possible criteria for what could be considered as *substantial progress*, and promising lines of research for the future, towards (more) automated ITP.

Keywords: Inductive theorem proving, automated theorem proving, automation, interaction, strategies, proof search control, challenges.



https://www.logic.at/staff/gramlich/



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Strategic Issues, Problems and Challenges in Inductive Theorem Proving

Bernhard Gramlich¹



In the near future, ITP (Inductive theorem proving) will only be successful for very specialised domains for very restricted classes of conjectures.

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Keywords: Inductive theorem proving, automated theorem proving, automation, interaction, strategies, proof search control, challenges.



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we are convinced that ... spectacular breakthroughs are unrealistic, in view of the enormous problems and the inherent difficulty of inductive theorem proving. (2005)

Keywords: Inductive theorem proving, automated theorem proving, automation, interaction, strategies, proof search control, challenges.

Proof by induction is important. Proof by induction is hard. Proof by induction is important.

Proof by induction is hard.



Proof by induction is important.

Proof by induction is hard.

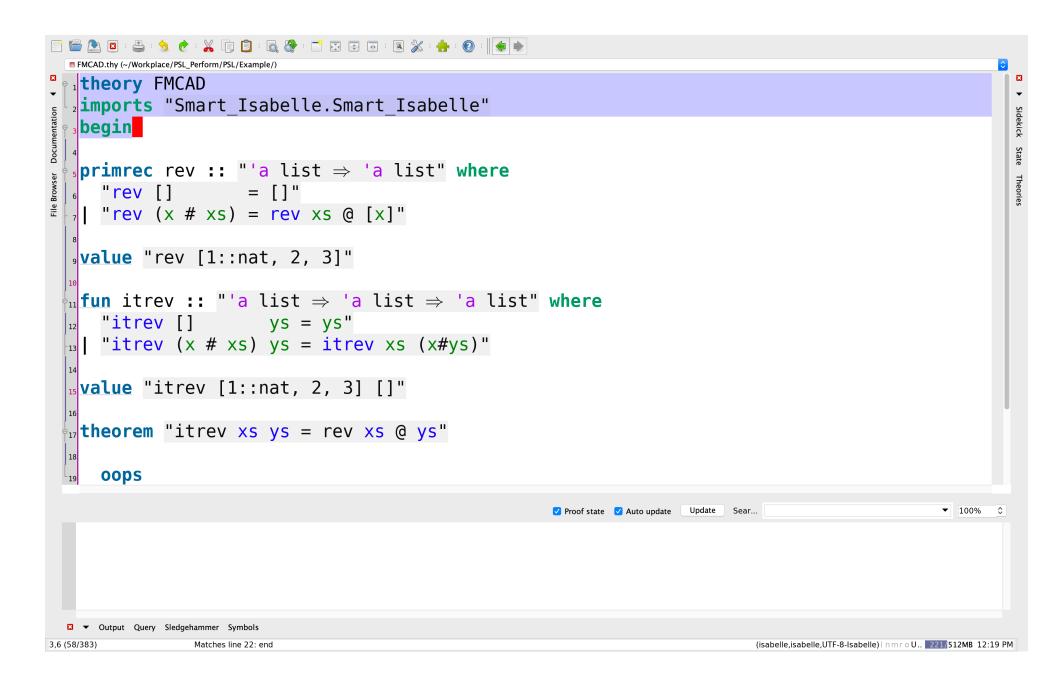
Proof by induction is important.

Proof by induction is hard.

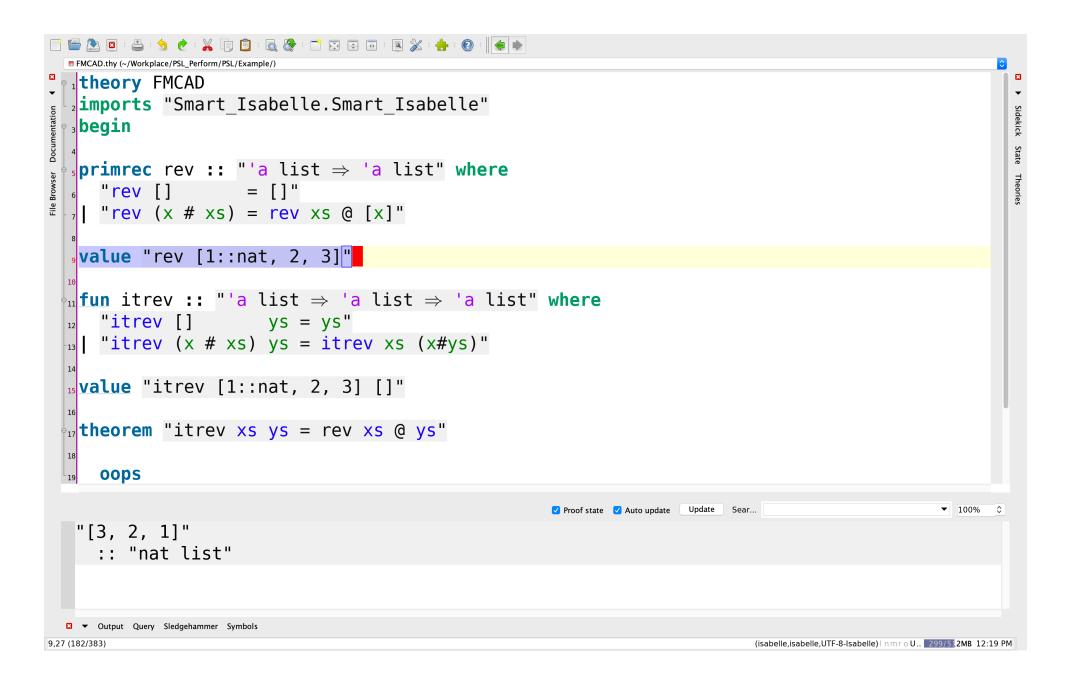
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proof by induction in Isabelle/HOL

The example theorem is taken from "Isabelle/HOL A Proof Assistant for Higher-Order Logic" Tobias Nipkow, Lawrence C. Paulson, Markus Wenzel page 36



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  1 theory FMCAD
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  <sup>2</sup> imports "Smart Isabelle.Smart Isabelle"
File Browser Documentation
                                                                                                                      Sidekick State Theories
  <sub>3</sub>begin
   primrec rev :: "'a list \Rightarrow 'a list" where
     "rev [] = []"
     "rev (x # xs) = rev xs @ [x]"
  value "rev [1::nat, 2, 3]"
 fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] ys = ys"
  12
 15 value "itrev [1::nat, 2, 3] []"
 hin theorem "itrev xs ys = rev xs @ ys"
  18
     oops
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   consts
     rev :: "'a list \Rightarrow 'a list"
 Output Query Sledgehammer Symbols
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  1 theory FMCAD
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  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
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File Browser Documentation
   <sub>3</sub>begin
                                                                                                                              State
   primrec rev :: "'a list \Rightarrow 'a list" where
                                                                                                                              Theories
     "rev [] = []"
   _{7} | "rev (x # xs) = rev xs @ [x]"
   value "rev [1::nat, 2, 3]"
 fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] vs = vs"
  12
     "itrev (x # xs) ys = itrev xs (x#ys)"
  13
  15 value "itrev [1::nat, 2, 3] []"
 h<sub>17</sub>theorem "itrev xs ys = rev xs @ ys"
  18
     oops
                                                                                                                    ▼ 100% ≎
                                                                 ✓ Proof state ✓ Auto update Update Sear...
   consts
      itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list"
   Found termination order: "(\lambda p. length (fst p)) <*mlex*> {}"
  Output Query Sledgehammer Symbols
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13,40 (299/383)

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  FMCAD.thy (~/Workplace/PSL_Perform/PSL/Example/)
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•
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  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
File Browser Documentation
                                                                                                                               Sidekick
   Jbegin
                                                                                                                               State Theories
   primrec rev :: "'a list \Rightarrow 'a list" where
    "rev [] = []"
   "rev (x # xs) = rev xs @ [x]"
   value "rev [1::nat, 2, 3]"
  \phi_{11} fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] ys = ys"
  12
  "itrev (x # xs) ys = itrev xs (x#ys)"
  value "itrev [1::nat, 2, 3] []"
  here witrev xs ys = rev xs @ ys"
  18
     oops
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                                                                  ✓ Proof state ✓ Auto update Update Sear...
   "[3, 2, 1]"
     :: "nat list"
  Output Query Sledgehammer Symbols
15,32 (332/383)
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   1 theory FMCAD
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  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
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File Browser Documentation
   <sub>3</sub>begin
                                                                                                                          State
   primrec rev :: "'a list \Rightarrow 'a list" where
                                                                                                                          Theories
     "rev [] = []"
   "rev (x # xs) = rev xs @ [x]"
   value "rev [1::nat, 2, 3]"
  \phi_{11} fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] ys = ys"
  12
  15 value "itrev [1::nat, 2, 3] []"
  theorem "itrev xs ys = rev xs @ ys"
  18
     oops
                                                                                                                 ▼ 100% ♦
                                                               🗸 Proof state 🗸 Auto update 🛛 Update 🚽 Sear...
   proof (prove)
   goal (1 subgoal):
    1. itrev xs ys = FMCAD.rev xs @ ys
  Output Query Sledgehammer Symbols
17,36 (369/383)
                                                                                         (isabelle,isabelle,UTF-8-Isabelle) | nmroU. 82/512MB 12:19 PM
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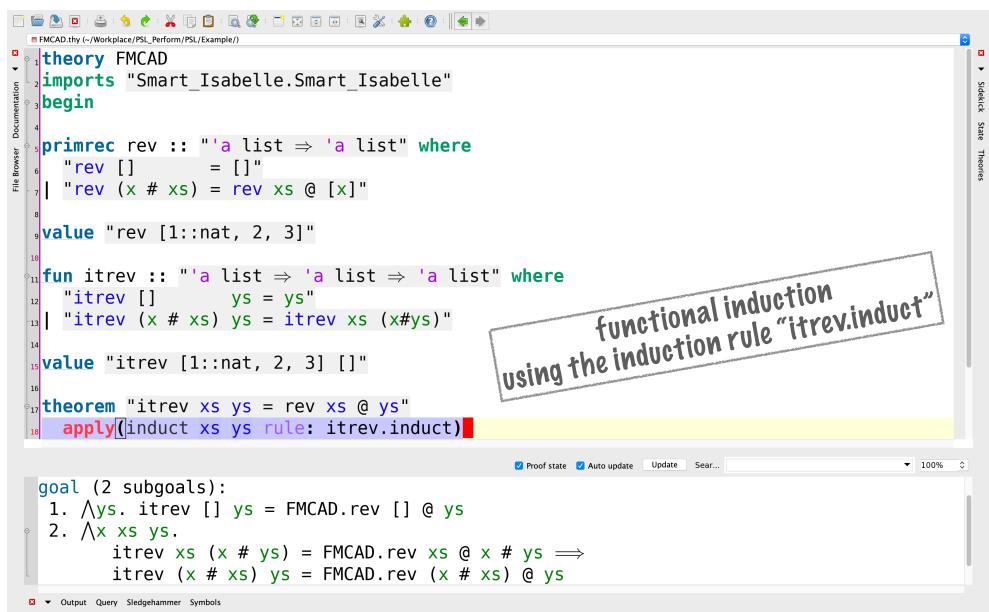
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  theory FMCAD
  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
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File Browser Documentation
  <sub>3</sub>begin
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   primrec rev :: "'a list \Rightarrow 'a list" where
                                                                                                                      Theories
     "rev [] = []"
  _{7} [ "rev (x # xs) = rev xs @ [x]"
  value "rev [1::nat, 2, 3]"
 fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] vs = vs"
  12
 |_{13} | "itrev (x # xs) ys = itrev xs (x#ys)"
  use "itrev [1::nat, 2, 3] []"
 hin theorem "itrev xs ys = rev xs @ ys"
     apply(induct xs ys rule: itrev.induct)
                                                             ✓ Proof state ✓ Auto update Update Sear...
                                                                                                             ▼ 100%
                                                                                                                    $
   goal (2 subgoals):
    1. \bigwedge ys. itrev [] ys = FMCAD.rev [] @ ys
    2. \bigwedge x x s y s.
            itrev xs (x # ys) = FMCAD.rev xs @ x # ys \implies
            itrev (x # xs) ys = FMCAD.rev (x # xs) @ ys
```

🖸 🔻 Output Query Sledgehammer Symbols

18,41 (410/423)

Matches line 1: theory FMCAD

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18,41 (410/423)

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  1 theory FMCAD
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  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
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File Browser Documentation
  <sub>3</sub>begin
                                                                                                                   State
  primrec rev :: "'a list \Rightarrow 'a list" where
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     "rev [] = []"
  "rev (x # xs) = rev xs @ [x]"
  value "rev [1::nat, 2, 3]"
 \phi_{11} fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] ys = ys"
  12
 15 value "itrev [1::nat, 2, 3] []"
 heorem "itrev xs ys = rev xs @ ys"
     apply(induct xs ys rule: itrev.induct)apply auto
done
                                                            ✓ Proof state ✓ Auto update Update Sear...
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   proof (prove)
   goal:
   No subgoals!
 Output Query Sledgehammer Symbols
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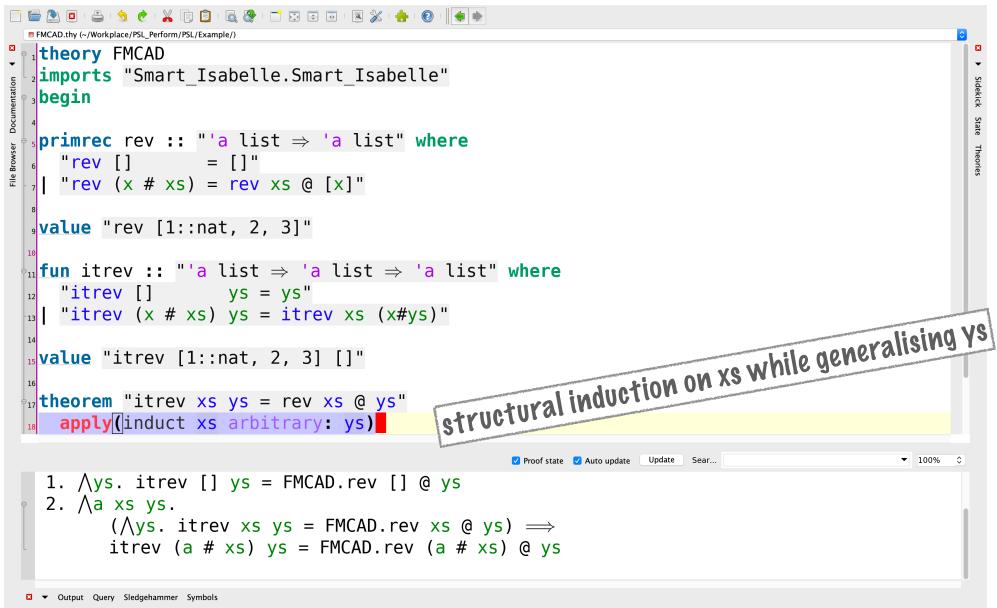
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  theory FMCAD
  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
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File Browser Documentation
  <sub>3</sub>begin
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   primrec rev :: "'a list \Rightarrow 'a list" where
                                                                                                                          Theories
    "rev [] = []"
  _{7} | "rev (x # xs) = rev xs @ [x]"
  value "rev [1::nat, 2, 3]"
 fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] vs = vs"
  12
  |_{13} | "itrev (x # xs) ys = itrev xs (x#ys)"
  use "itrev [1::nat, 2, 3] []"
 h<sub>17</sub> theorem "itrev xs ys = rev xs @ ys"
    apply(induct xs arbitrary: ys)
                                                               ✓ Proof state ✓ Auto update Update Sear...
                                                                                                                ▼ 100% $\lambda$
    1. \Lambdays. itrev [] ys = FMCAD.rev [] @ ys
    2. ∧a xs ys.
            (\Lambda ys. itrev xs ys = FMCAD.rev xs @ ys) \implies
            itrev (a # xs) ys = FMCAD.rev (a # xs) @ ys
  Output Query Sledgehammer Symbols
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18,33 (402/414)

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18,33 (402/414)

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  primrec rev :: "'a list \Rightarrow 'a list" where
     "rev [] = []"
  "rev (x # xs) = rev xs @ [x]"
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 \phi_{11} fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] ys = ys"
  12
 15 value "itrev [1::nat, 2, 3] []"
 hear "itrev xs ys = rev xs @ ys"
     apply(induct xs arbitrary: ys) apply auto done
                                                            ✓ Proof state ✓ Auto update Update Sear...
                                                                                                          ▼ 100% $\lambda$
   proof (prove)
   goal:
   No subgoals!
 Output Query Sledgehammer Symbols
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     "rev [] = []"
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     "itrev [] ys = ys"
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 15 value "itrev [1::nat, 2, 3] []"
 hin theorem "itrev xs ys = rev xs @ ys"
 18 try hard
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   proof (prove)
   goal (1 subgoal):
   1. itrev xs ys = FMCAD.rev xs @ ys
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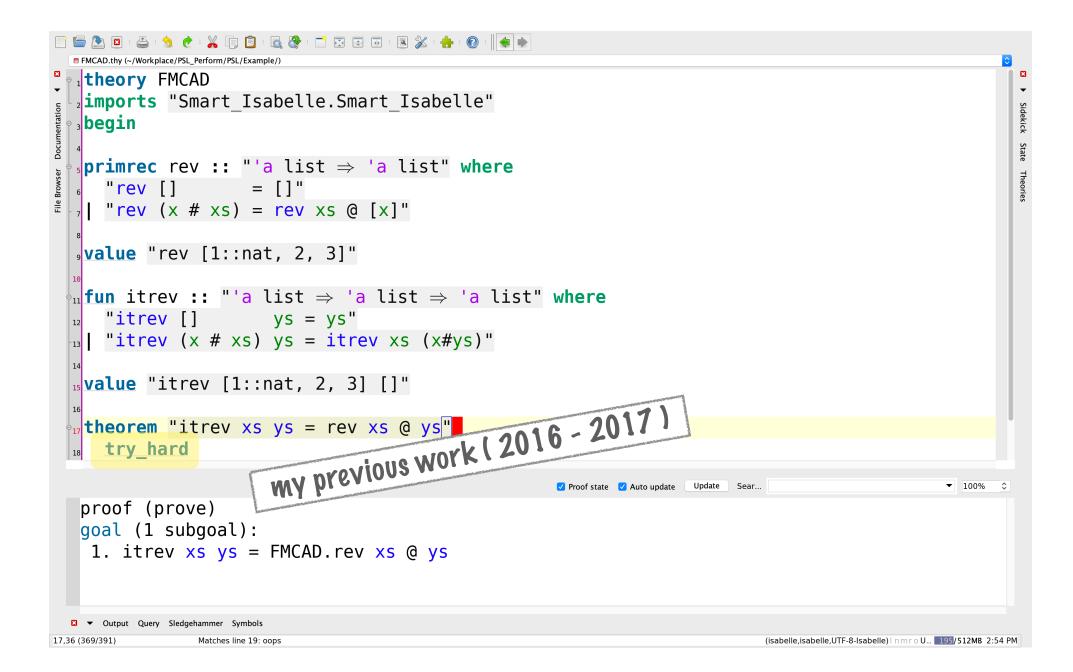
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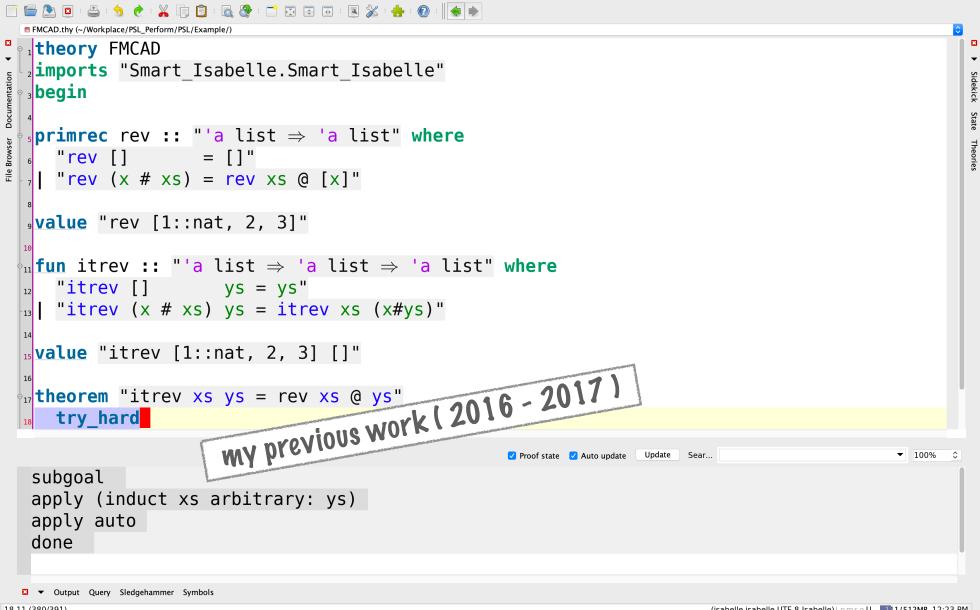
17,36 (369/391)

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     "rev [] = []"
  "rev (x # xs) = rev xs @ [x]"
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 hin theorem "itrev xs ys = rev xs @ ys"
 18 try hard
                                                             ✓ Proof state ✓ Auto update Update Sear...
                                                                                                            ▼ 100% $\lambda$
   proof (prove)
   goal (1 subgoal):
   1. itrev xs ys = FMCAD.rev xs @ ys
  Output Query Sledgehammer Symbols
```

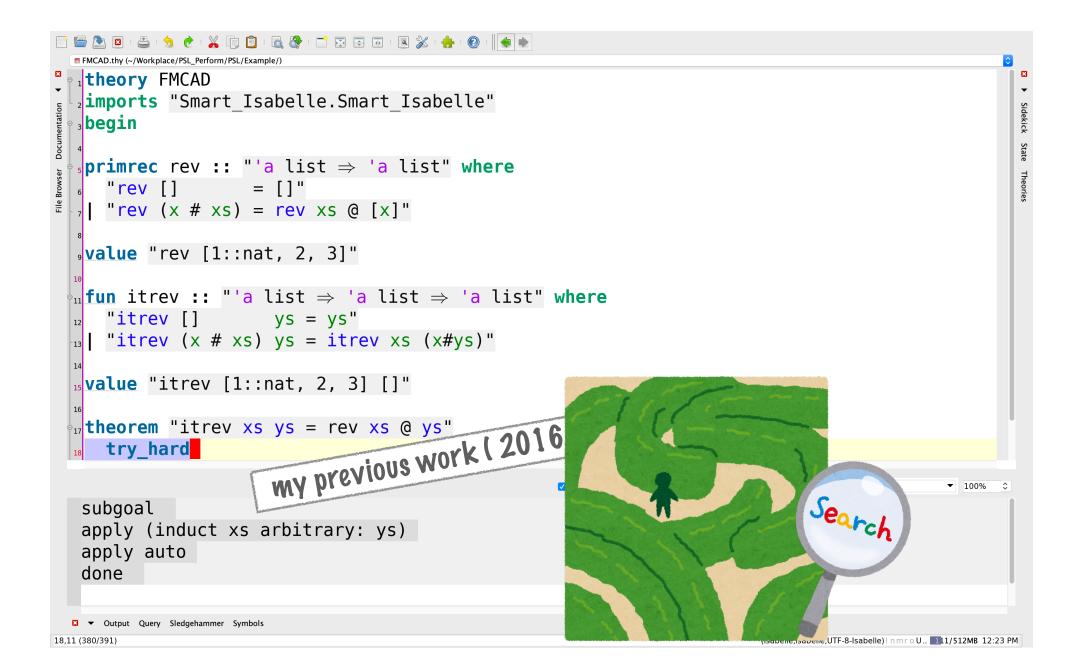
17,36 (369/391)

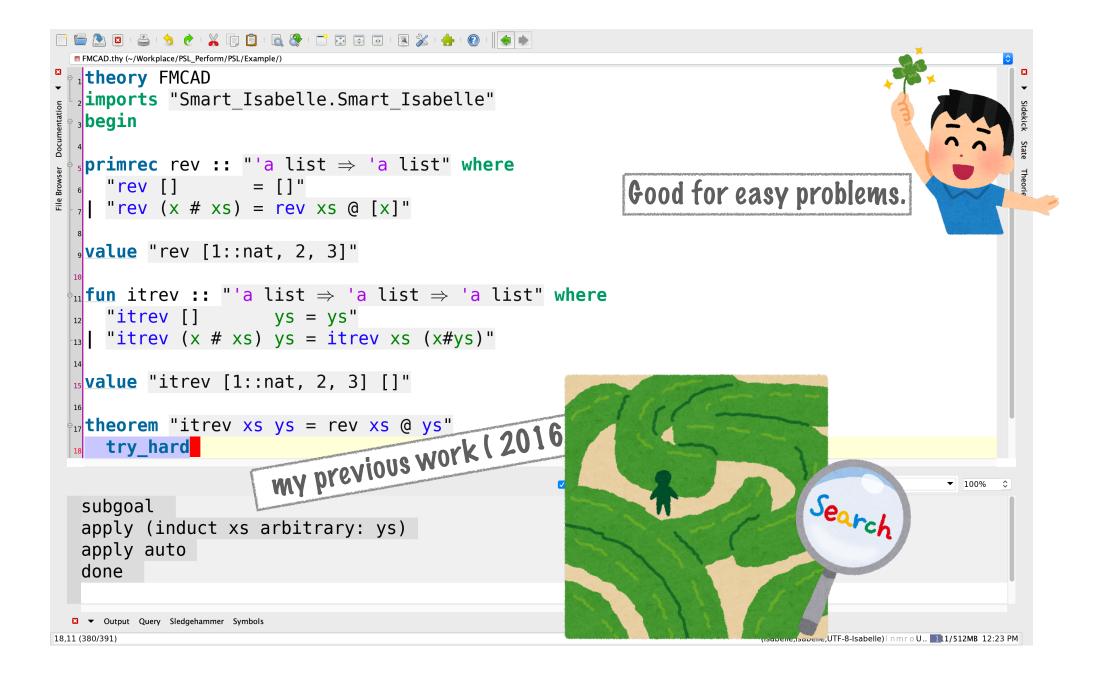


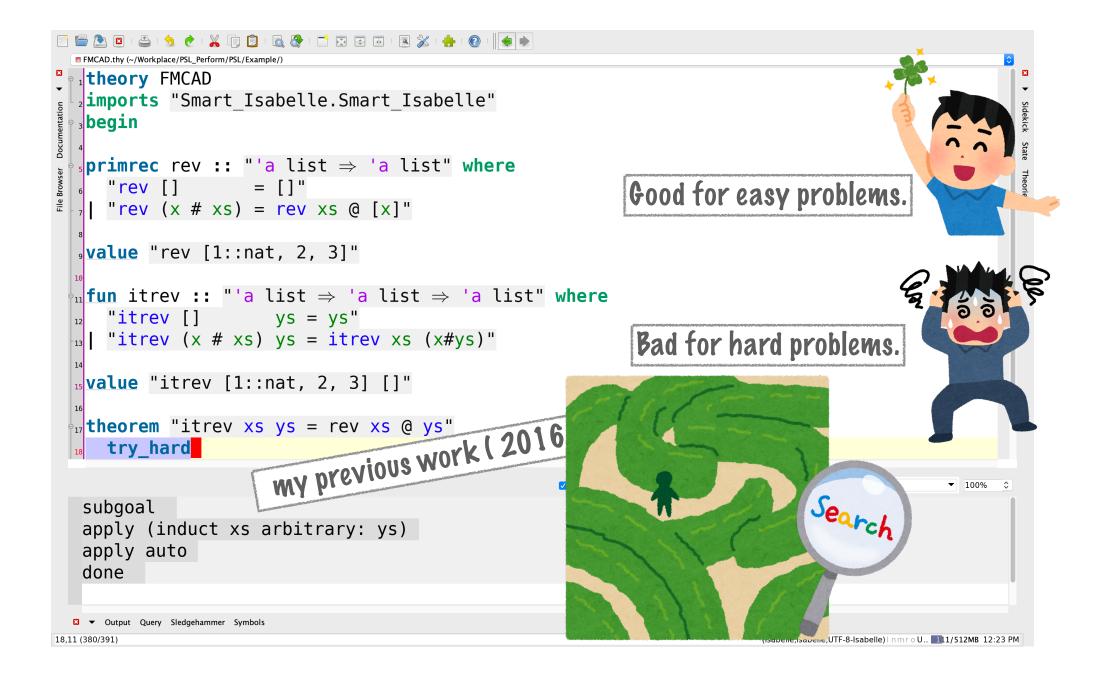


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Bad news for automation.

(For most cases) we only have to pass the right arguments to the induction tactic.

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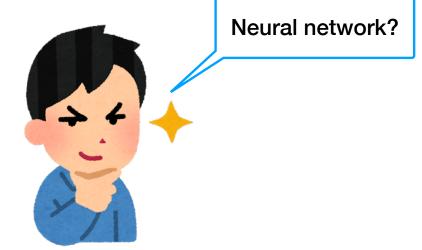
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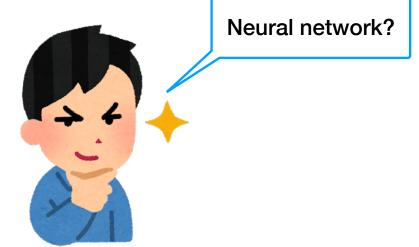
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All theorems must be different.

We should not have many similar theorems.

lemma "itrev xs ys = rev xs @ ys"
by(induct xs ys rule:"itrev.induct") auto



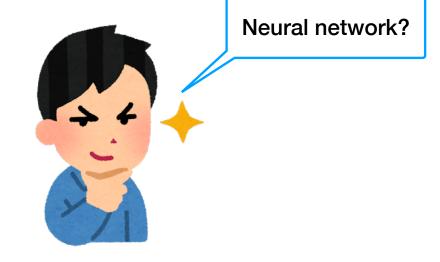
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We should not have many similar theorems.



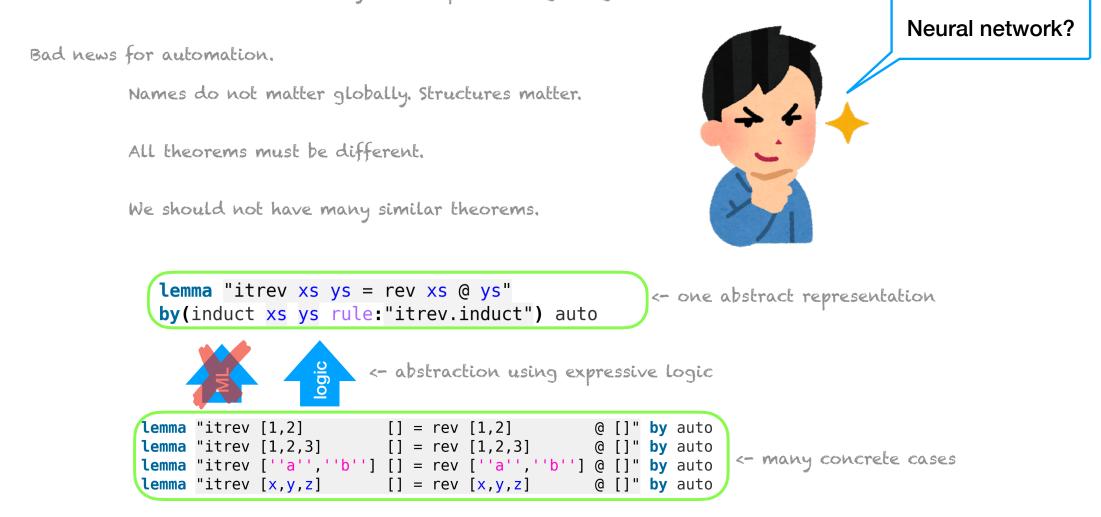
lemma "itrev xs ys = rev xs @ ys"
by(induct xs ys rule:"itrev.induct") auto

<- one abstract representation

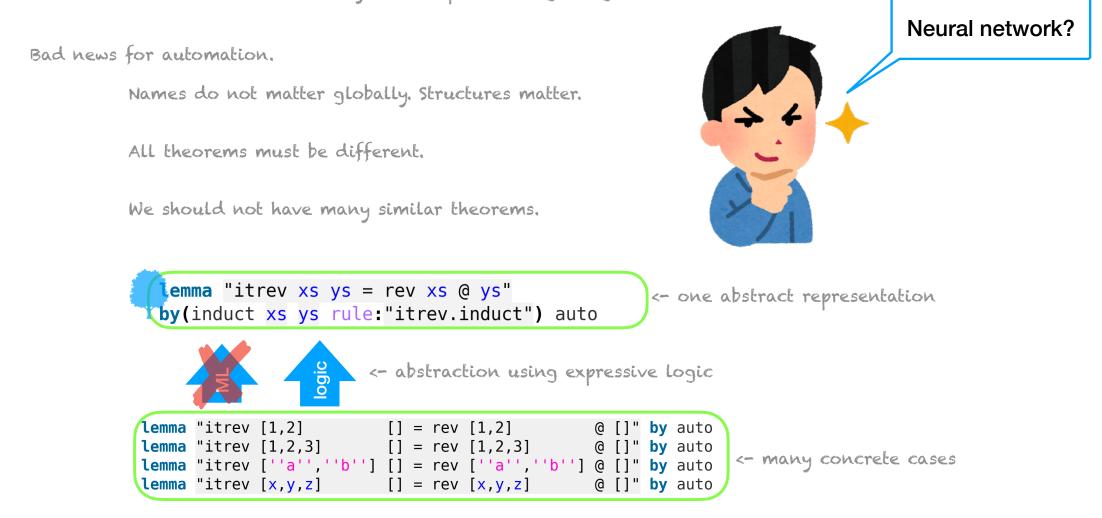
<pre>lemma "itrev lemma "itrev lemma "itrev lemma "itrev</pre>	[1,2,3] [''a'',''b'']	[] = rev [''a'',''b'']	<pre>@ []" by auto @ []" by auto @ []" by auto @ []" by auto @ []" by auto</pre>	<- many con
--	--------------------------	------------------------	--	-------------

- many concrete cases

(For most cases) we only have to pass the right arguments to the induction tactic.



(For most cases) we only have to pass the right arguments to the induction tactic.



Many key challenges remain

Unsupervised Learning

Memory and one-shot learning

Imagination-based Planning with Generative Models

Learning Abstract Concepts

Transfer Learning

Language understanding





March 20, 2019

The Power of Self-Learning Systems

Many key challenges remain

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The Power of Self-Learning Systems

logic?

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March 20, 2019

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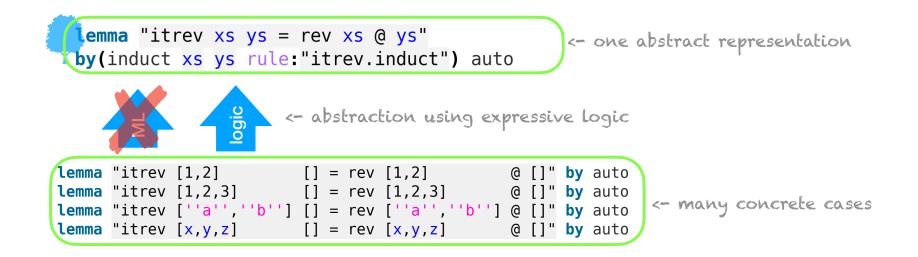
LiFtEr: Logical Feature Extraction

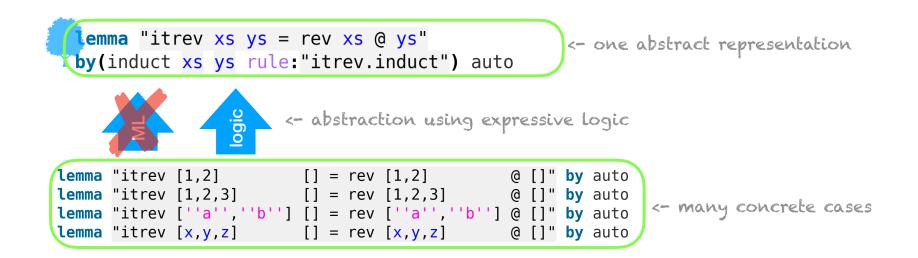


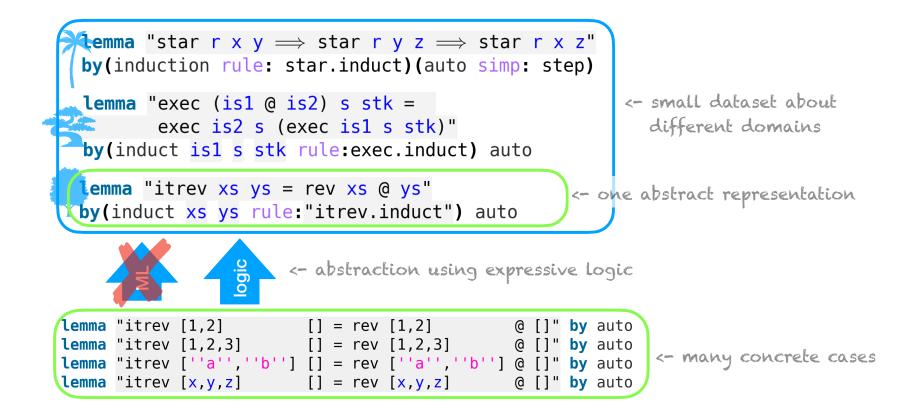


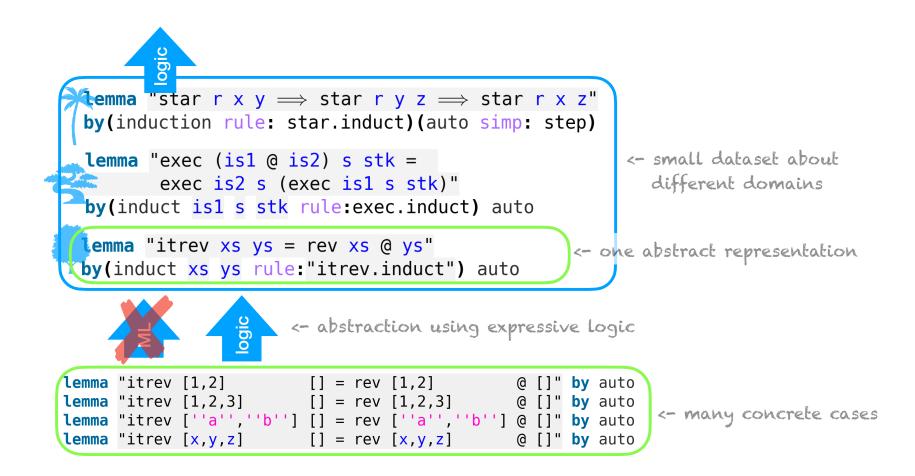
March 20, 2019

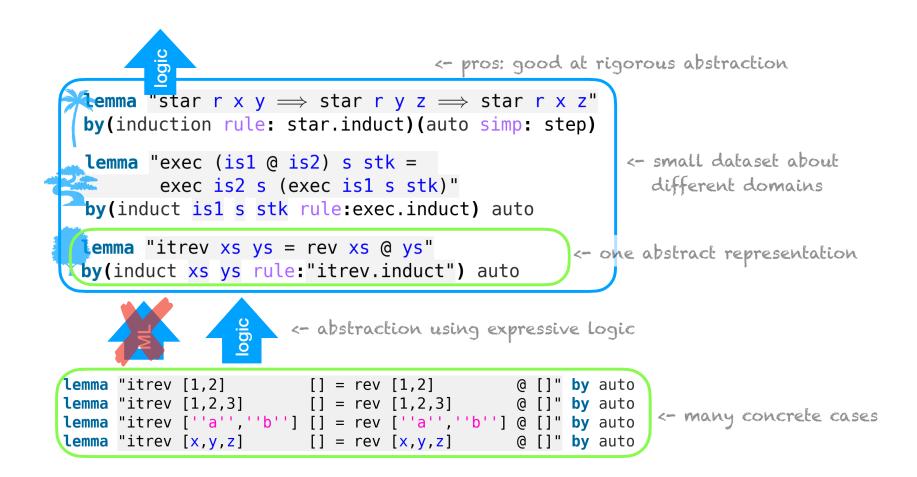
The Power of Self-Learning Systems

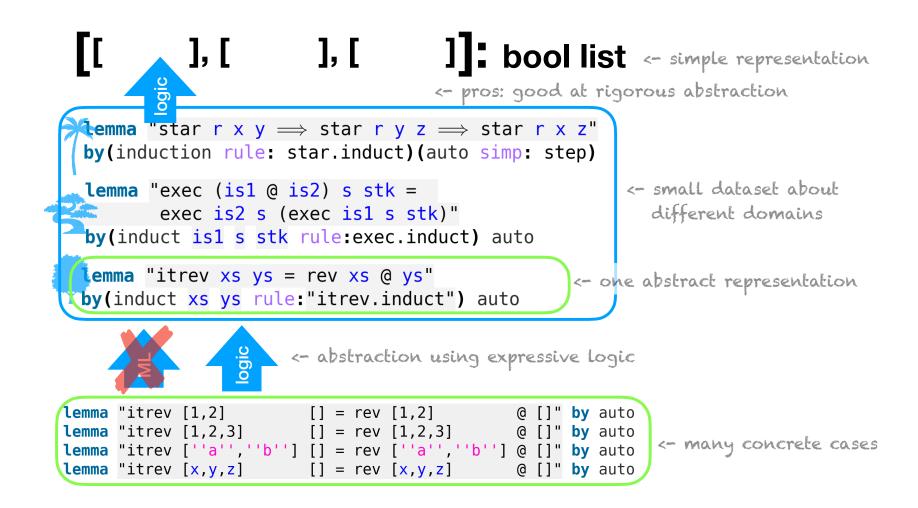


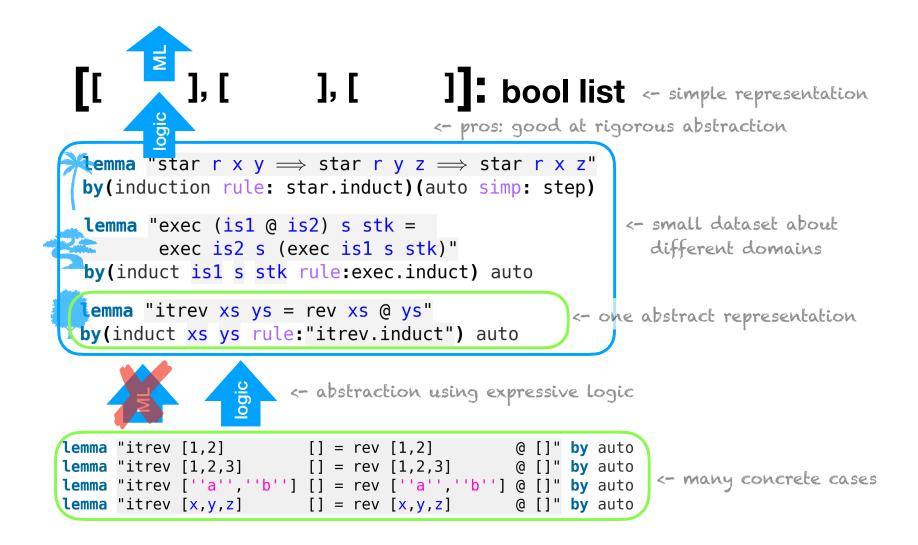


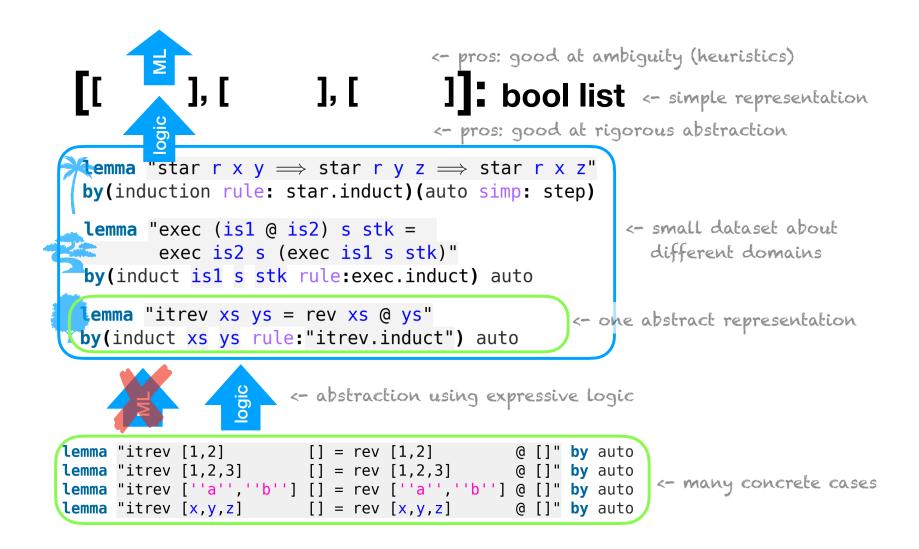




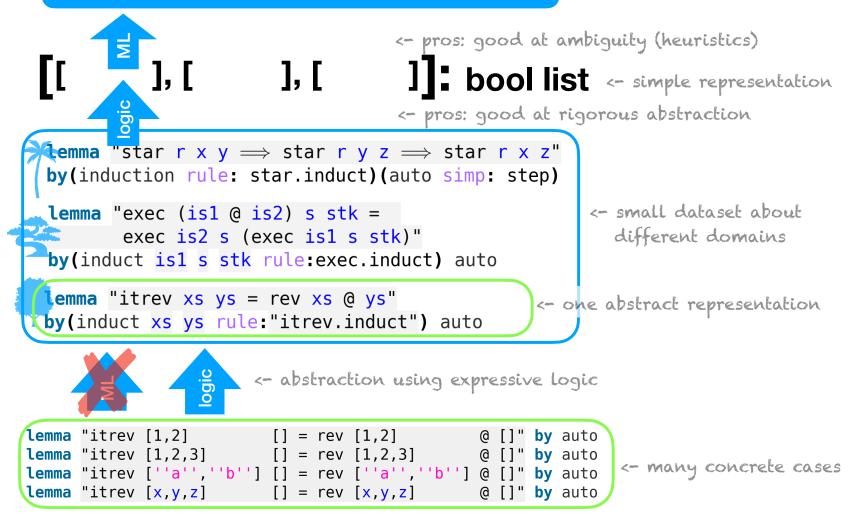


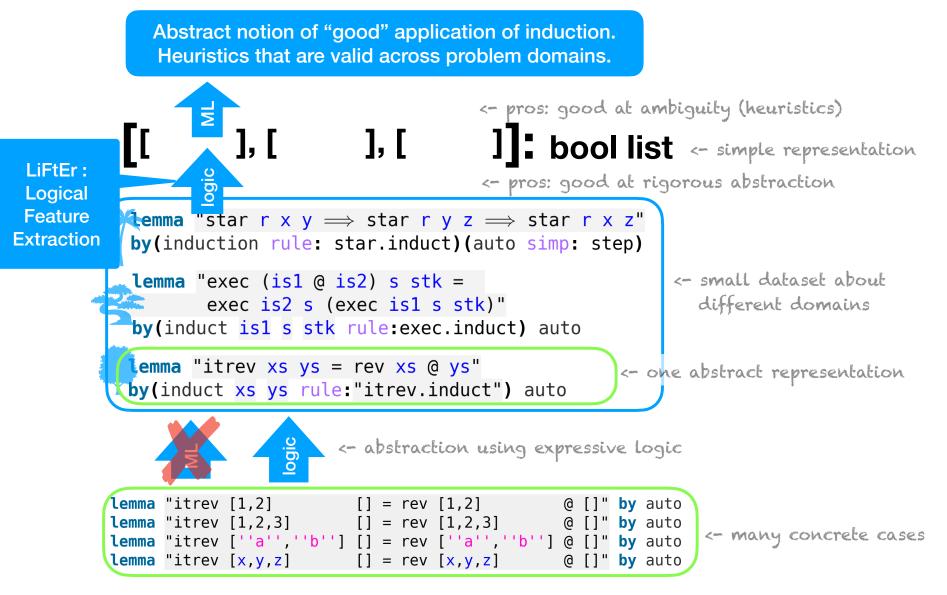






Abstract notion of "good" application of induction. Heuristics that are valid across problem domains.

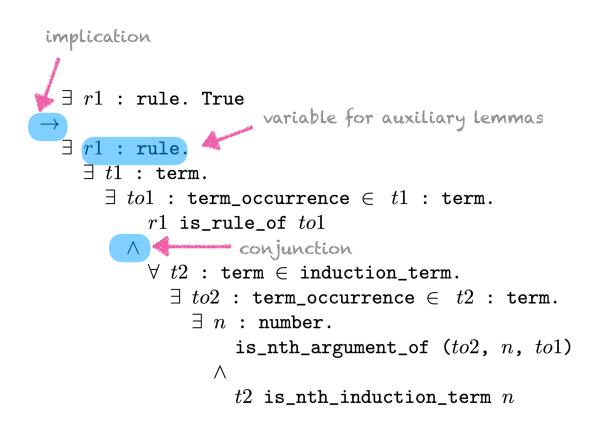


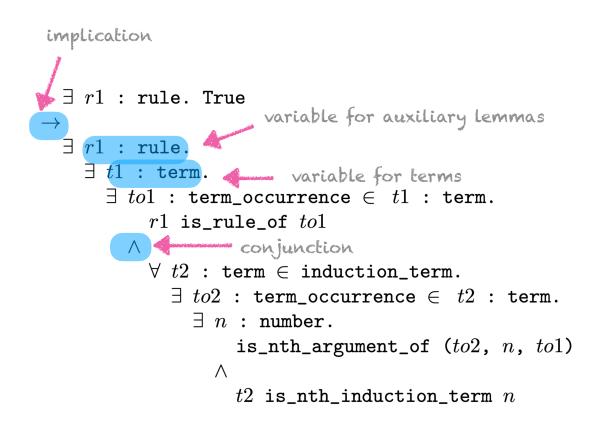


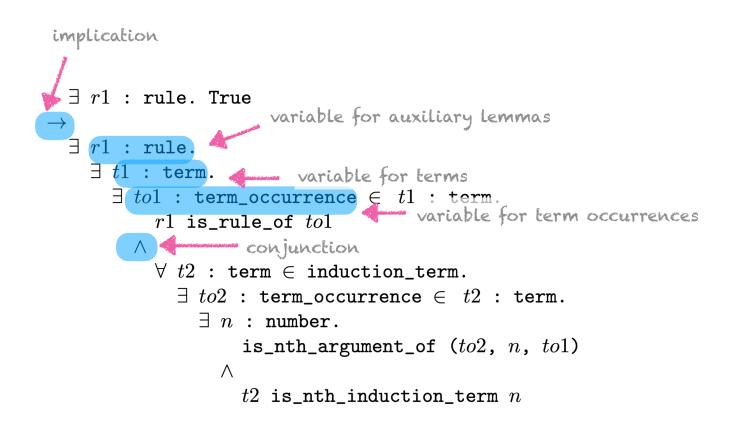
```
\exists r1 : rule. True
\Rightarrow
\exists r1 : rule.
\exists t1 : term.
\exists to1 : term_occurrence \in t1 : term.
r1 is_rule_of to1
\land
\forall t2 : term \in induction_term.
\exists to2 : term_occurrence \in t2 : term.
\exists n : number.
is_nth_argument_of (to2, n, to1)
\land
t2 is_nth_induction_term n
```

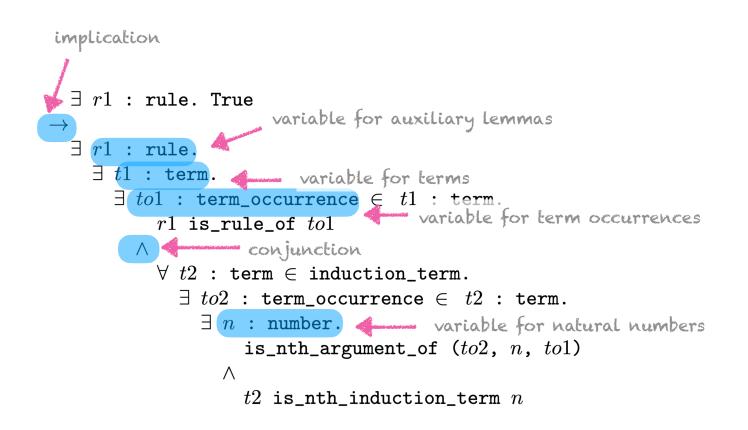
```
implication
\exists r1 : rule. True
<math display="block">\exists r1 : rule.
\exists t1 : term.
\exists to1 : term_occurrence \in t1 : term.
r1 is_rule_of to1
<math display="block">\land
\forall t2 : term \in induction_term.
\exists to2 : term_occurrence \in t2 : term.
\exists n : number.
is_nth_argument_of (to2, n, to1)
<math display="block">\land
t2 is_nth_induction_term n
```

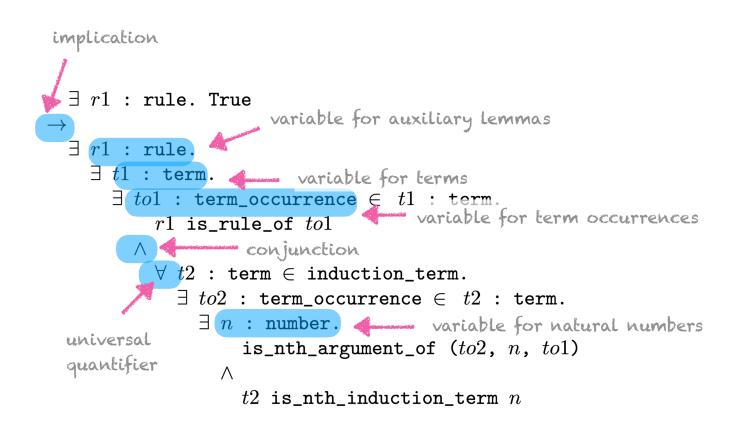
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\exists r1 : rule. True
<math display="block">\exists r1 : rule.
\exists t1 : term.
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is_nth_argument_of (to2, n, to1)
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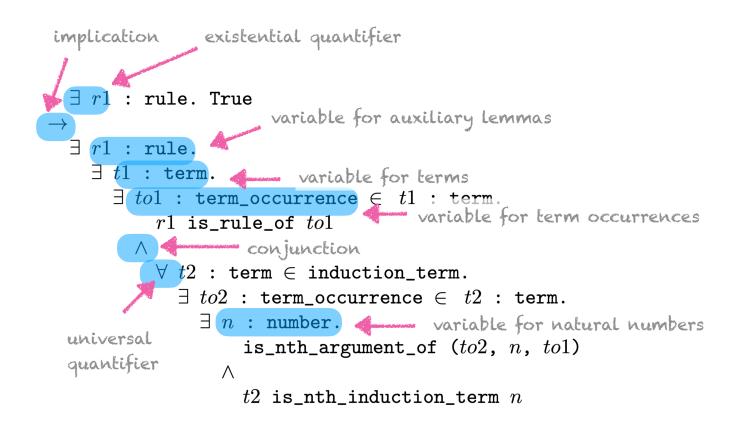




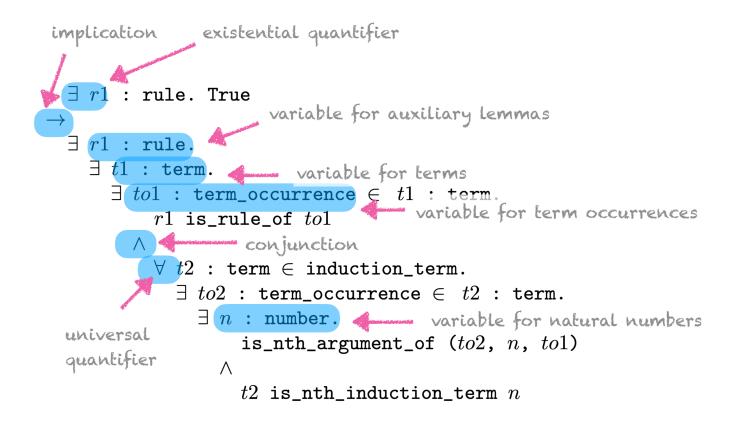




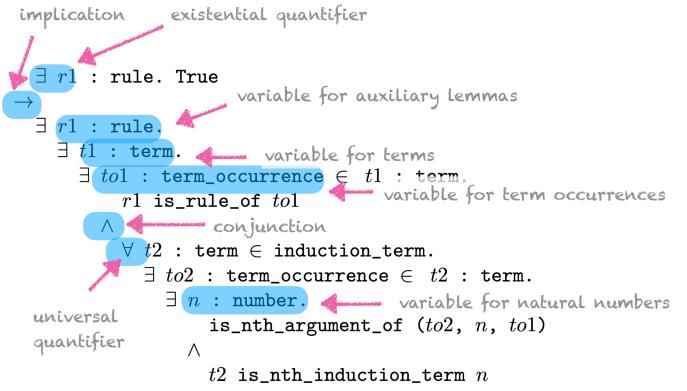




LiFtEr heuristic: (proof goal * induction arguments) -> bool



LiFtEr heuristic: (proof goal * induction arguments) -> bool should be <u>true</u> if induction is <u>good</u> should be <u>false</u> if induction is <u>bad</u>



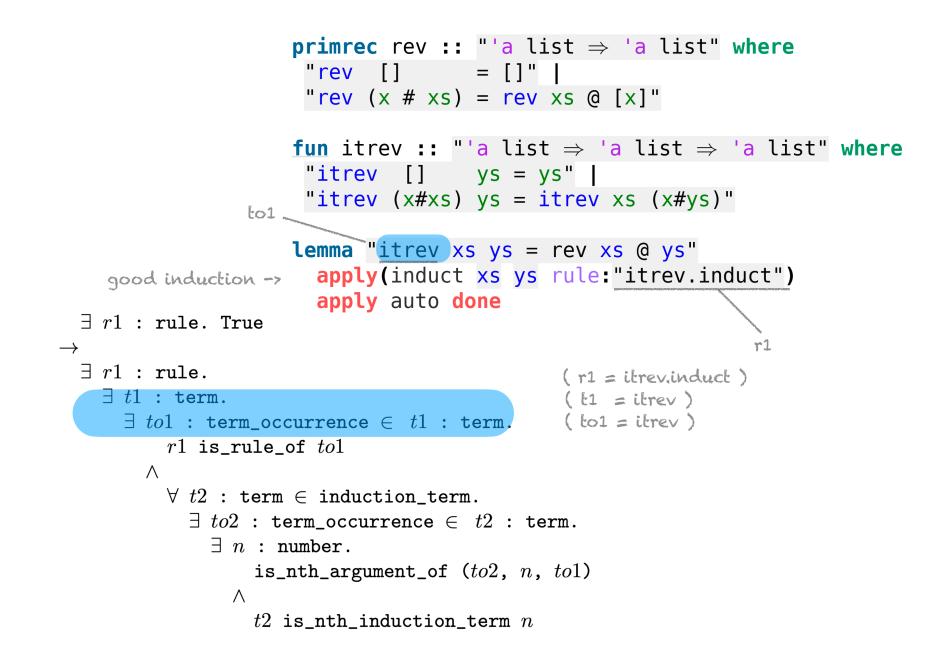
```
primrec rev :: "'a list \Rightarrow 'a list" where
                        "rev [] = []" |
                        "rev (x # xs) = rev xs @ [x]"
                       fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
                         "itrev [] ys = ys" |
                         "itrev (x#xs) ys = itrev xs (x#ys)"
                       lemma "itrev xs ys = rev xs @ ys"
                          apply(induct xs ys rule:"itrev.induct")
                          apply auto done
  \exists r1 : rule. True
\rightarrow
  \exists r1 : rule.
    \exists t1 : term.
      \exists to1 : term_occurrence \in t1 : term.
          r1 is_rule_of to1
        Λ
          \forall t2 : term \in induction\_term.
             \exists to2 : term_occurrence \in t2 : term.
               \exists n : \text{number}.
                   is_nth_argument_of (to2, n, to1)
                 Λ
                   t2 is_nth_induction_term n
```

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primrec rev :: "'a list \Rightarrow 'a list" where
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                       lemma "itrev xs ys = rev xs @ ys"
                         apply(induct xs ys rule:"itrev.induct")
    good induction ->
                          apply auto done
  \exists r1 : rule. True
\rightarrow
  \exists r1 : rule.
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    good induction ->
                         apply auto done
 \exists r1 : rule. True
                                                                      r1
\rightarrow
 \exists r1 : rule.
                                                  (r1 = itrev.induct)
    \exists t1 : term.
      \exists to1 : term_occurrence \in t1 : term.
          r1 is_rule_of to1
        Λ
          \forall t2 : term \in induction\_term.
            \exists to2 : term_occurrence \in t2 : term.
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                 Λ
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                       lemma "itrev xs ys = rev xs @ ys"
                          apply(induct xs ys rule:"itrev.induct")
    good induction ->
                          apply auto done
  \exists r1 : rule. True
                                                                      r1
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                                                   (r1 = itrev.induct)
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                 Λ
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                          apply(induct xs ys rule:"itrev.induct")
    good induction ->
                          apply auto done
  \exists r1 : rule. True
                                                                      r1
\rightarrow
  \exists r1 : rule.
                                                   (r1 = itrev.induct)
    \exists t1 : term.
                                                   (t1 = itrev)
      \exists to1 : term_occurrence \in t1 : term.
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                 Λ
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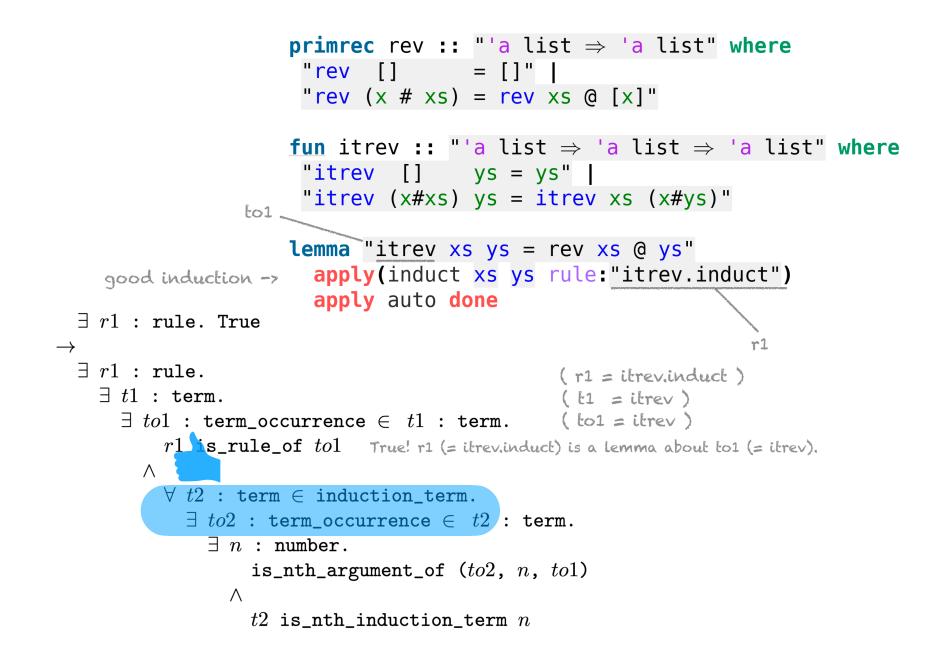


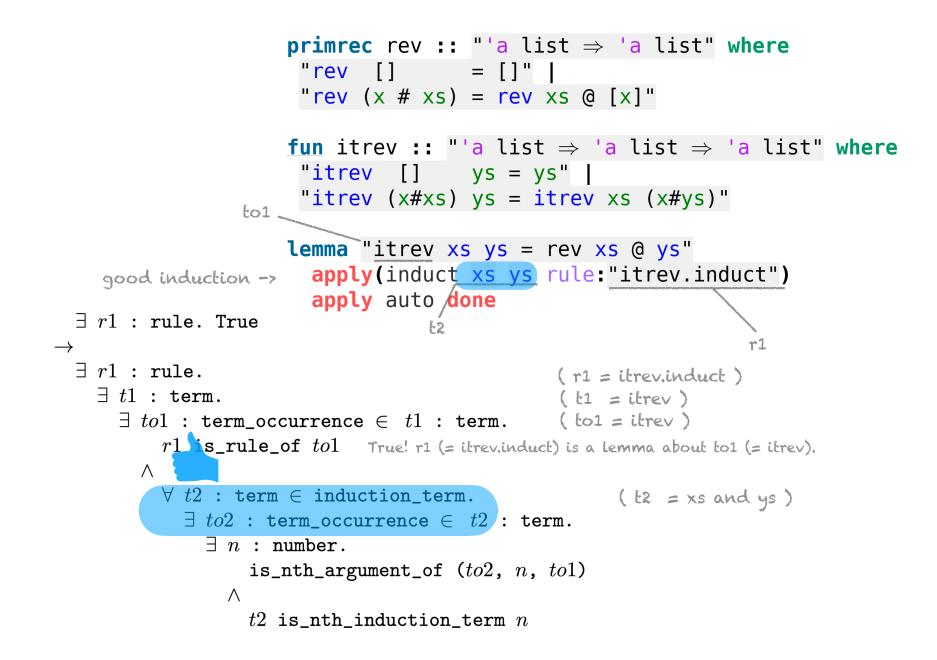
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                        "itrev (x#xs) ys = itrev xs (x#ys)"
                   to1
                       lemma "itrev xs ys = rev xs @ ys"
                         apply(induct xs ys rule:"itrev.induct")
    good induction ->
                         apply auto done
  \exists r1 : rule. True
                                                                      r1
\rightarrow
  \exists r1 : rule.
                                                  (r1 = itrev.induct)
    \exists t1 : term.
                                                  (t_1 = itrev)
      \exists to1 : term_occurrence \in t1 : term. (to1 = itrev)
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                   is_nth_argument_of (to2, n, to1)
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```

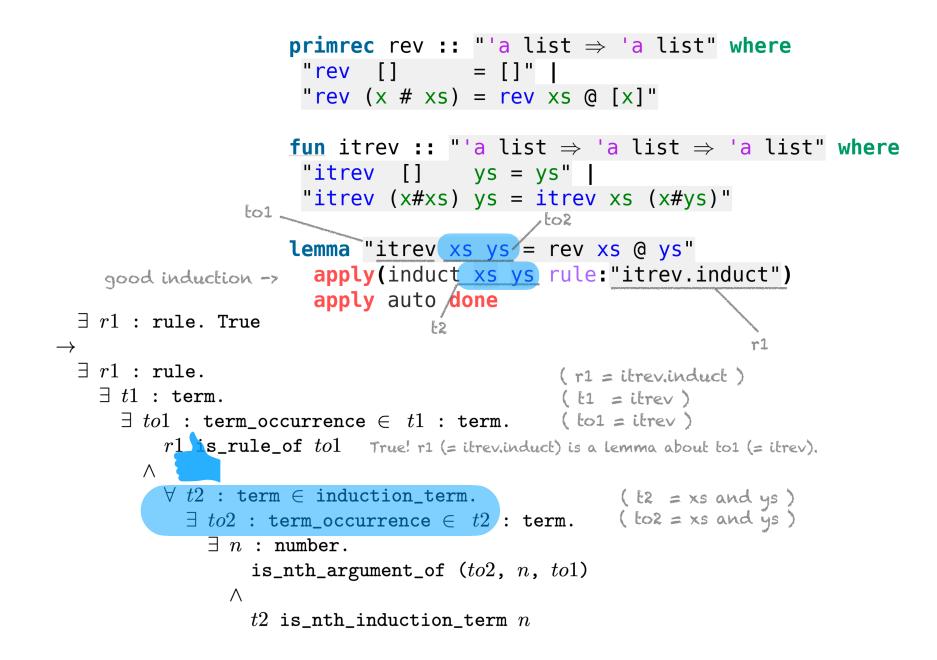
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                         "itrev (x#xs) ys = itrev xs (x#ys)"
                   to1 .
                        lemma "itrev xs ys = rev xs @ ys"
                          apply(induct xs ys rule:"itrev.induct")
     good induction ->
                          apply auto done
  \exists r1 : rule. True
                                                                       r1
\rightarrow
  \exists r1 : rule.
                                                   (r1 = itrev.induct)
    \exists t1 : term.
                                                   (t1 = itrev)
      \exists to1 : term_occurrence \in t1 : term. (to1 = itrev)
          r1 is_rule_of to1 True! r1 (= itrev.induct) is a lemma about to1 (= itrev).
         Λ
          \forall t2 : term \in induction\_term.
             \exists to2 : term_occurrence \in t2 : term.
               \exists n : \text{number}.
                    is_nth_argument_of (to2, n, to1)
                 Λ
                   t2 is_nth_induction_term n
```

```
primrec rev :: "'a list \Rightarrow 'a list" where
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                         "itrev (x#xs) ys = itrev xs (x#ys)"
                   to1 .
                        lemma "itrev xs ys = rev xs @ ys"
                          apply(induct xs ys rule:"itrev.induct")
     good induction ->
                          apply auto done
  \exists r1 : rule. True
                                                                       r1
\rightarrow
  \exists r1 : rule.
                                                   (r1 = itrev.induct)
    \exists t1 : term.
                                                   (t1 = itrev)
      \exists to1 : term_occurrence \in t1 : term. (to1 = itrev)
           <u>r1 is_rule_of</u> to1 True! r1 (= itrev.induct) is a lemma about to1 (= itrev).
         Λ
          \forall t2 : term \in induction\_term.
             \exists to2 : term_occurrence \in t2 : term.
               \exists n : number.
                    is_nth_argument_of (to2, n, to1)
                 Λ
                   t2 is_nth_induction_term n
```

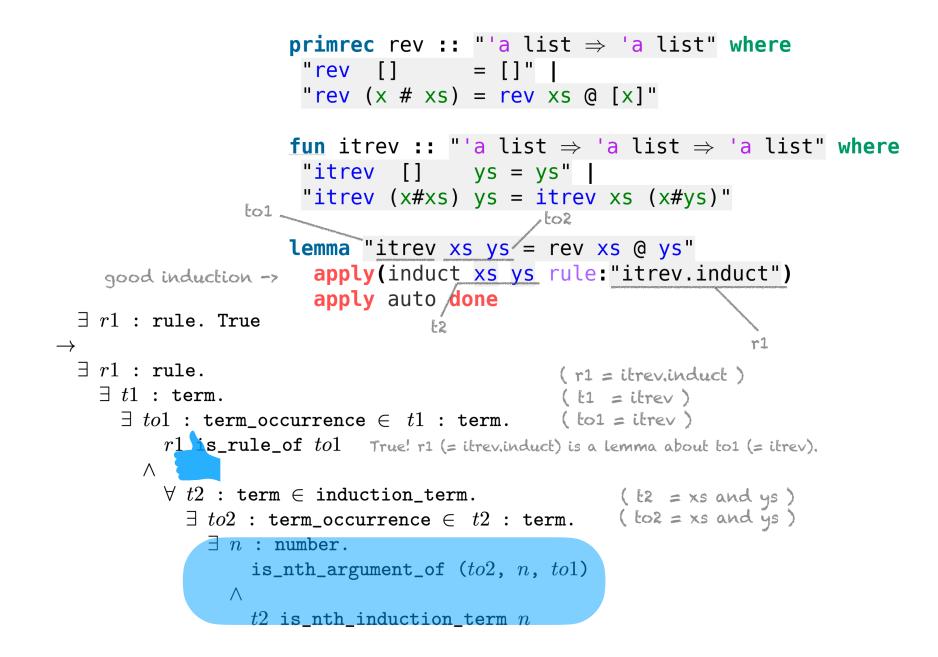
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                         "itrev [] ys = ys" |
                         "itrev (x#xs) ys = itrev xs (x#ys)"
                   to1
                       lemma "itrev xs ys = rev xs @ ys"
                          apply(induct xs ys rule:"itrev.induct")
     good induction ->
                          apply auto done
  \exists r1 : rule. True
                                                                       r1
\rightarrow
  \exists r1 : rule.
                                                   (r1 = itrev.induct)
    \exists t1 : term.
                                                   (t1 = itrev)
      \exists to1 : term_occurrence \in t1 : term. (to1 = itrev)
          r1_is_rule_of to1 True! r1 (= itrev.induct) is a lemma about to1 (= itrev).
        Λ
          \forall t2 : term \in induction\_term.
             \exists to2 : term_occurrence \in t2 : term.
               \exists n : \text{number}.
                   is_nth_argument_of (to2, n, to1)
                 Λ
                   t2 is_nth_induction_term n
```

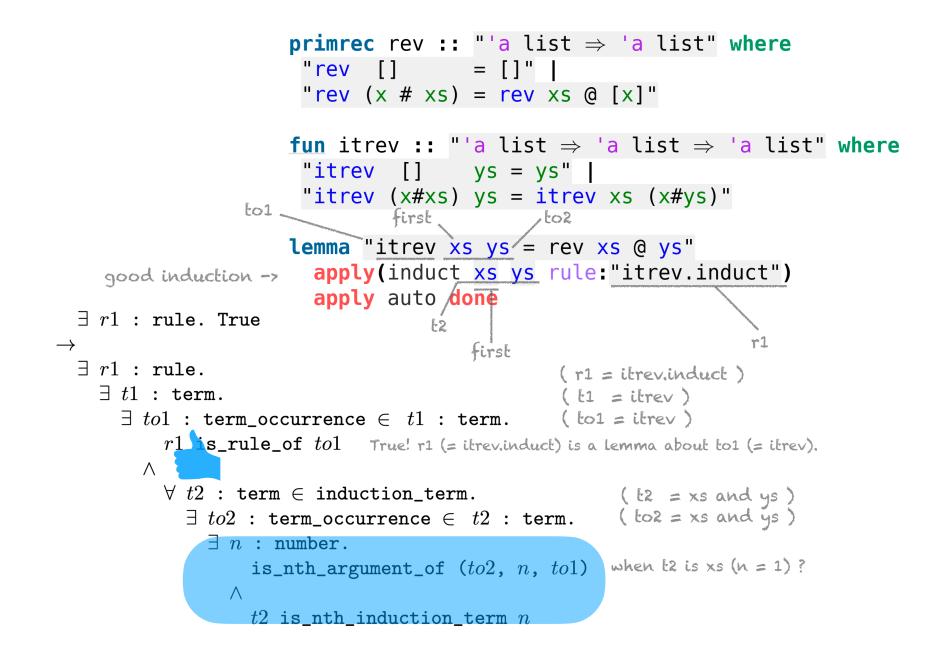


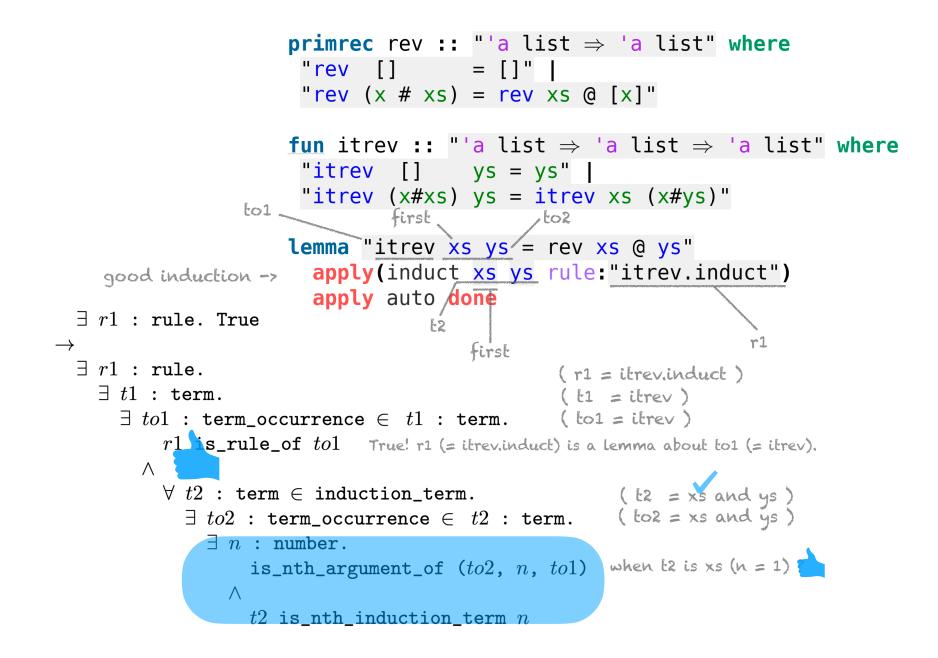


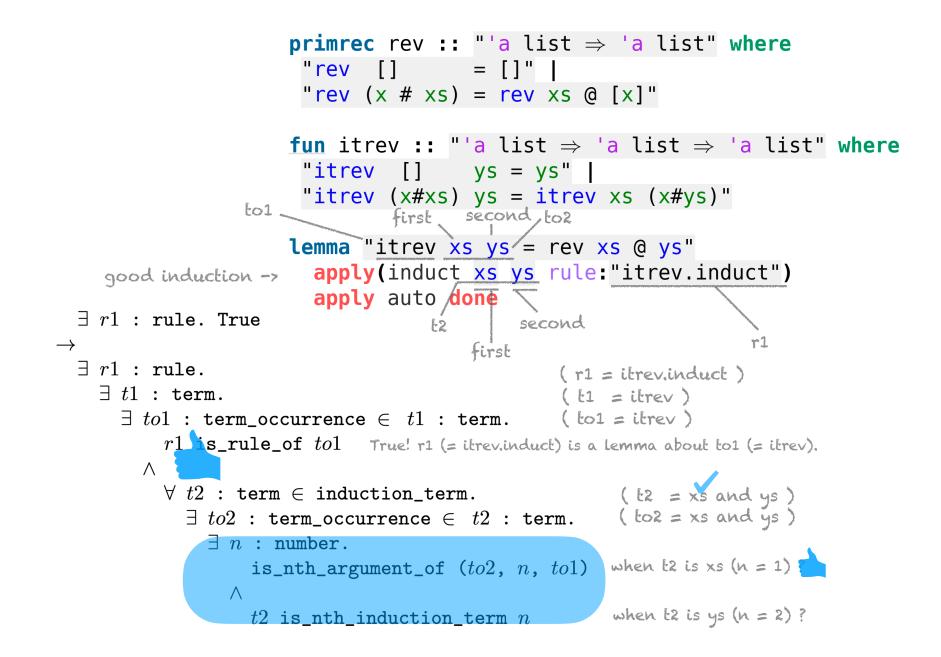


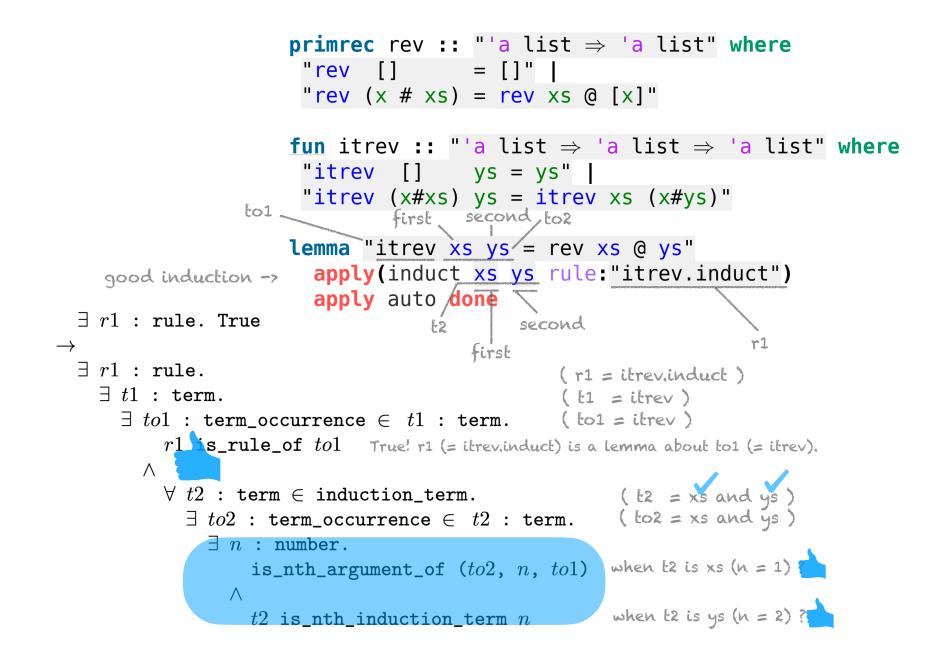
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primrec rev :: "'a list \Rightarrow 'a list" where
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                          "itrev [] ys = ys" |
                         "itrev (x#xs) ys = itrev xs (x#ys)"
                   to1 .
                                                  , to2
                        lemma "itrev xs ys = rev xs @ ys"
     good induction -> apply(induct xs ys rule: "itrev.induct")
                          apply auto done
  \exists r1 : rule. True
                                       £2
                                                                         r1
\rightarrow
  \exists r1 : rule.
                                                    (r1 = itrev, induct)
    \exists t1 : term.
                                                    (t1 = itrev)
      \exists to1 : term_occurrence \in t1 : term. (to1 = itrev)
           r1 s_rule_of to1 True! r1 (= itrev.induct) is a lemma about to1 (= itrev).
         Λ
           \forall t2 : term \in induction\_term.
                                              (t_2 = x_s and y_s)
: term. (t_{02} = x_s and y_s)
             \exists to2 : term_occurrence \in t2 : term.
               \exists n : \text{number}.
                    is_nth_argument_of (to2, n, to1)
                  Λ
                    t2 is_nth_induction_term n
```

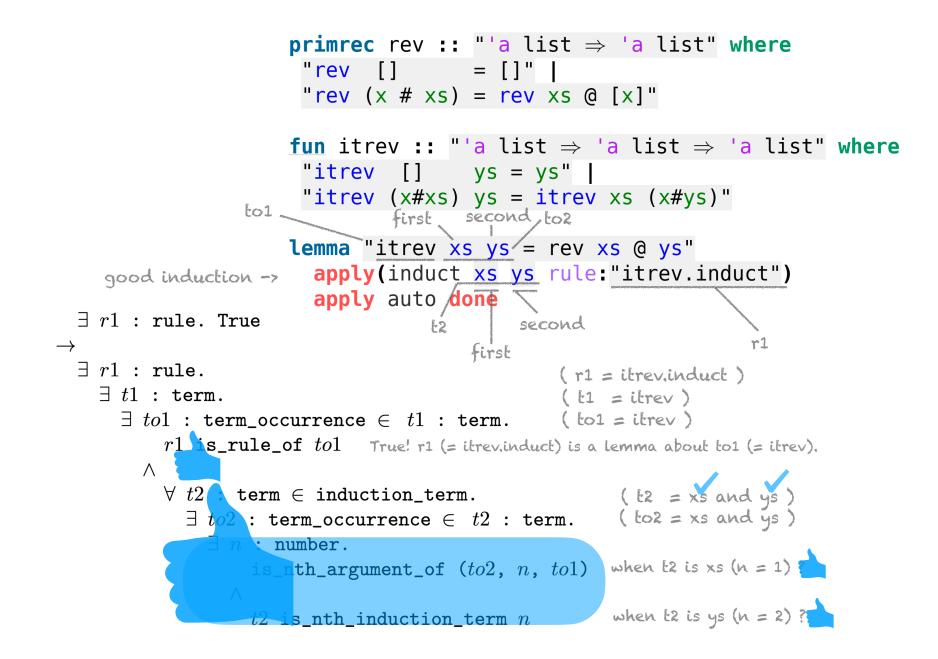


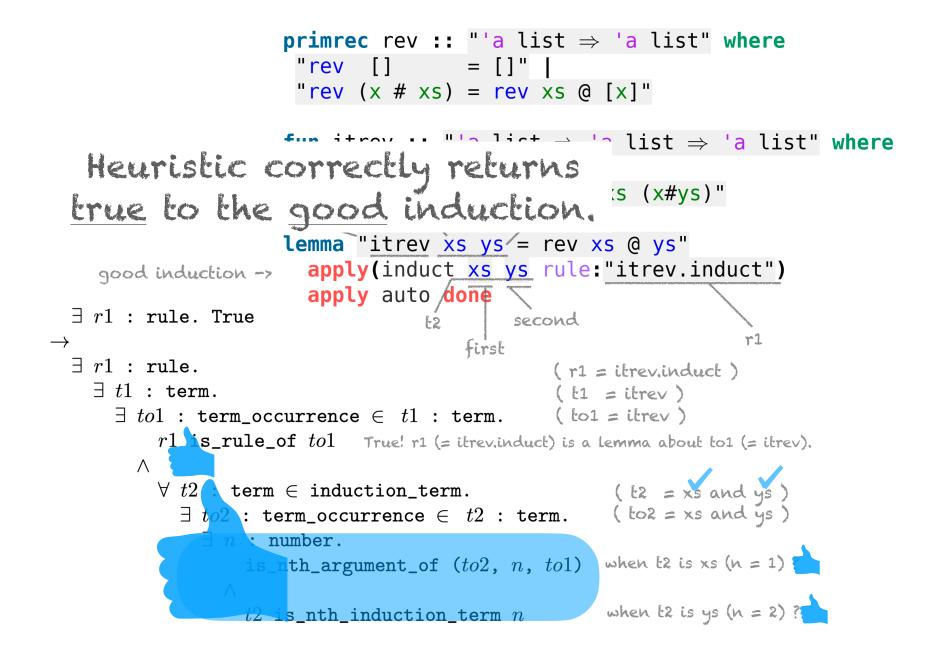


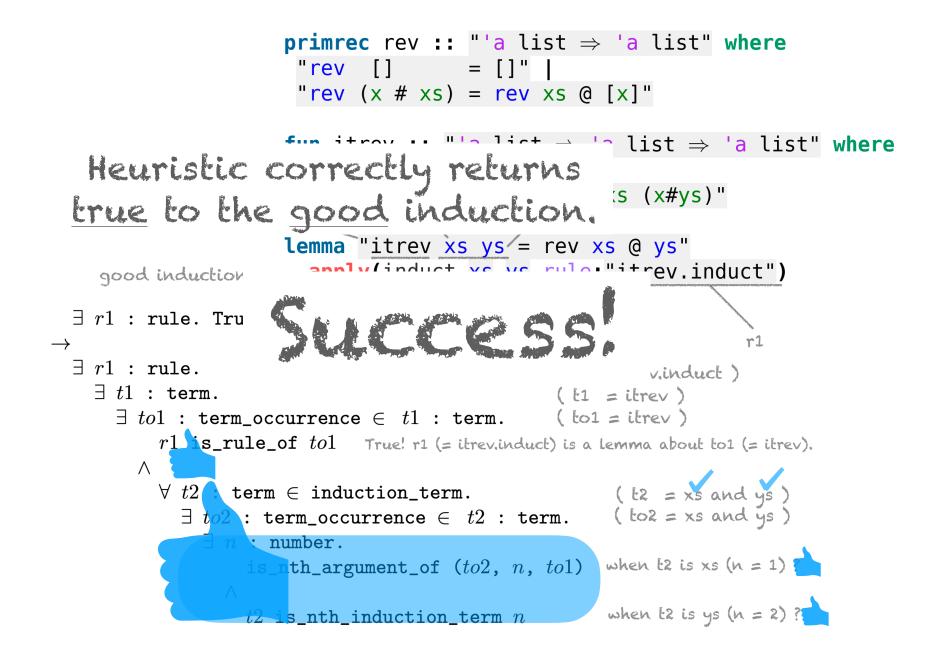












```
\exists r1 : rule. True
\Rightarrow
\exists r1 : rule.
\exists t1 : term.
\exists to1 : term_occurrence \in t1 : term.
r1 is_rule_of to1
\land
\forall t2 : term \in induction_term.
\exists to2 : term_occurrence \in t2 : term.
\exists n : number.
is_nth_argument_of (to2, n, to1)
\land
t2 is_nth_induction_term n
```

```
\exists r1 : rule. True
\Rightarrow \\ \exists r1 : rule. \\ \exists tr1 : term. \\ \exists to1 : term_occurrence \in t1 : term. \\ r1 is_rule_of to1 \\ \land \\ \forall t2 : term \in induction_term. \\ \exists to2 : term_occurrence \in t2 : term. \\ \exists n : number. \\ is_nth_argument_of (to2, n, to1) \\ \land \\ t2 is_nth_induction_term n
```

```
primrec rev :: "'a list ⇒ 'a list" where
                      "rev [] = []" |
                      "rev (x # xs) = rev xs @ [x]"
                     fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
                      "itrev [] ys = ys" |
                      "itrev (x#xs) ys = itrev xs (x#ys)"
                     lemma "itrev xs ys = rev xs @ ys"
                      apply(induct ys xs rule: itrev.induct)
 \exists r1 : rule. True apply auto oops
\rightarrow
                                                        the same LiFtEr heuristic
  \exists r1 : rule.
    \exists t1 : term.
      \exists to1 : term_occurrence \in t1 : term.
          r1 is_rule_of to1
        Λ
          \forall t2 : term \in induction\_term.
            \exists to2 : term_occurrence \in t2 : term.
              \exists n : \text{number}.
                   is_nth_argument_of (to2, n, to1)
                 Λ
                   t2 is_nth_induction_term n
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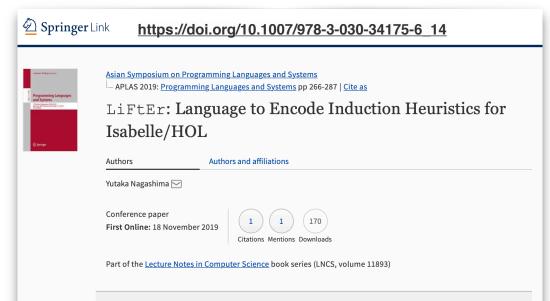
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Abstract

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Yutaka Nagashima 🖂

Authors

Authors and affiliations

Conference paper First Online: 18 November 2019

Isabelle/HOL

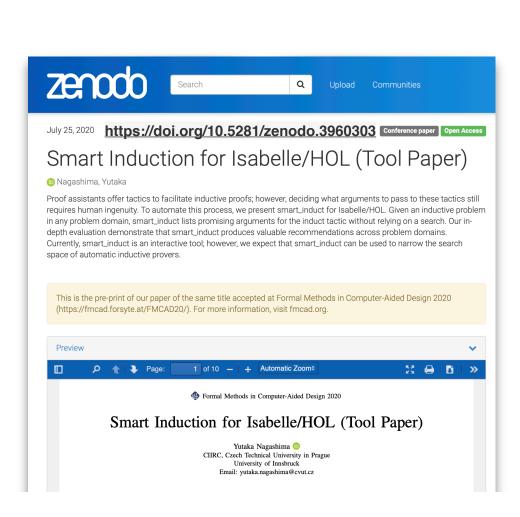
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Lifter: Language to Encode Induction Heuristics for

Part of the Lecture Notes in Computer Science book series (LNCS, volume 11893)

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On which variables to apply induction

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les	LiFtEr :Lan	guage to Encode Induction Heuristics for
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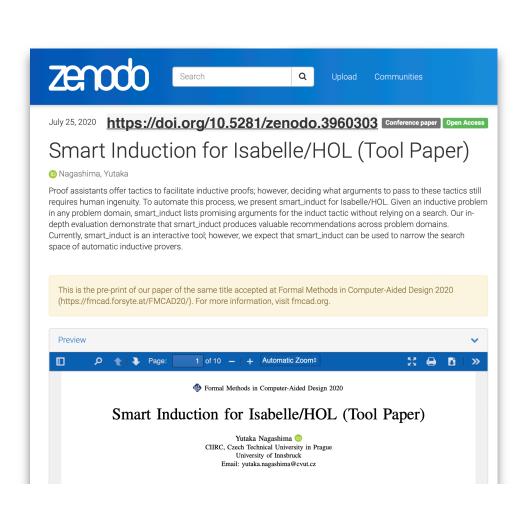
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Variable generalisation

July 25, 2020 https://doi.org/10.5281/zenodo.3960303 Conference paper

Smart Induction for Isabelle/HOL (Tool Paper) • Nagashima, Yutaka

zenodo

Proof assistants offer tactics to facilitate inductive proofs; however, deciding what arguments to pass to these tactics still requires human ingenuity. To automate this process, we present smart_induct for Isabelle/HOL. Given an inductive problem in any problem domain, smart_induct lists promising arguments for the induct tactic without relying on a search. Our indepth evaluation demonstrate that smart_induct produces valuable recommendations across problem domains. Currently, smart_induct is an interactive tool; however, we expect that smart_induct can be used to narrow the search space of automatic inductive provers.

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Open Access

This is the pre-print of our paper of the same title accepted at Formal Methods in Computer-Aided Design 2020 (https://fmcad.forsyte.at/FMCAD20/). For more information, visit fmcad.org.

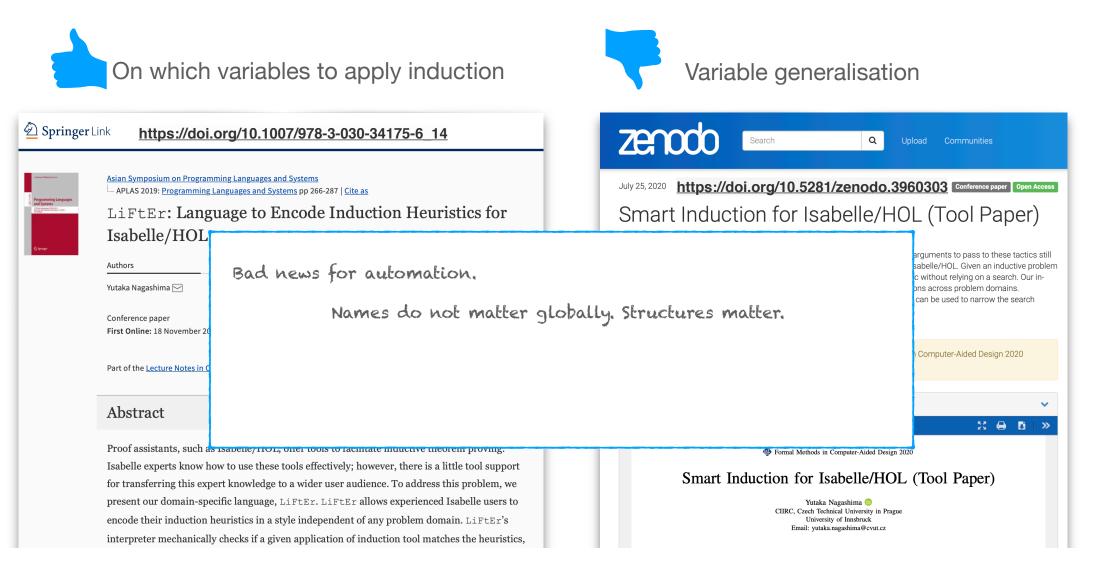


🏇 Formal Methods in Computer-Aided Design 2020

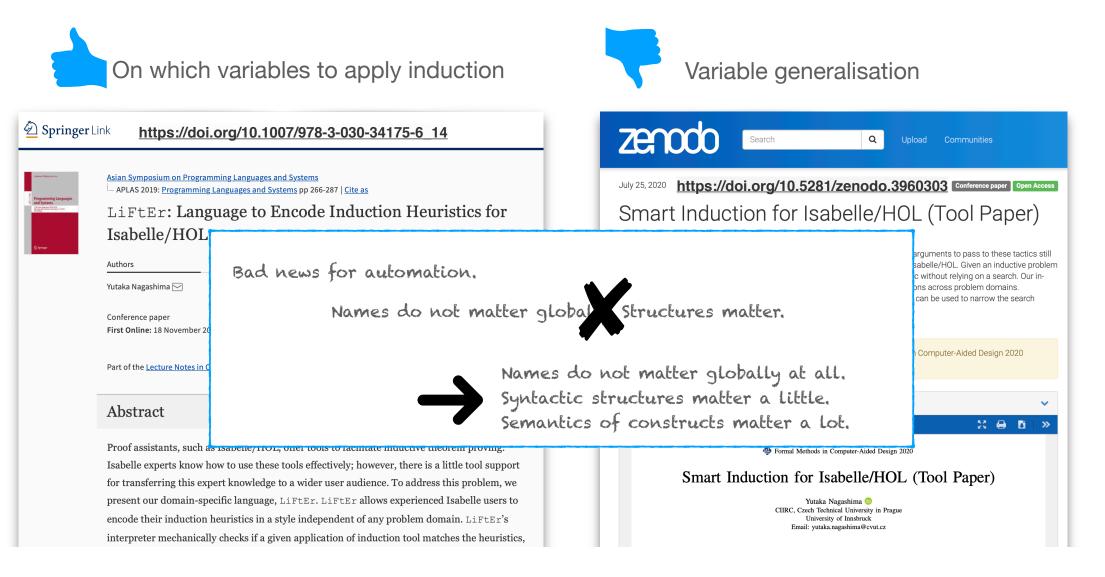
Smart Induction for Isabelle/HOL (Tool Paper)

Yutaka Nagashima 🙃 CIIRC, Czech Technical University in Prague University of Innsbruck Email: yutaka.nagashima@cvut.cz

LiFtEr at APLAS2019 and Smart Induct at FMCAD2020 (nest week)



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primrec rev :: "'a list ⇒ 'a list" where
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Generalize goals for induction by universally quantifying all free variables (except the induction variable itself!).

This prevents trivial failures like the one above and does not affect the validity of the goal. However, this heuristic should not be applied blindly. It is not always required, and the additional quantifiers can complicate matters in some cases. The variables that should be quantified are typically those that change in recursive calls.

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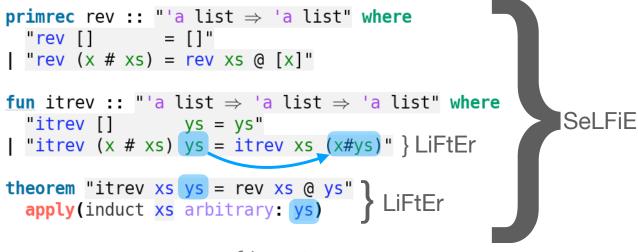
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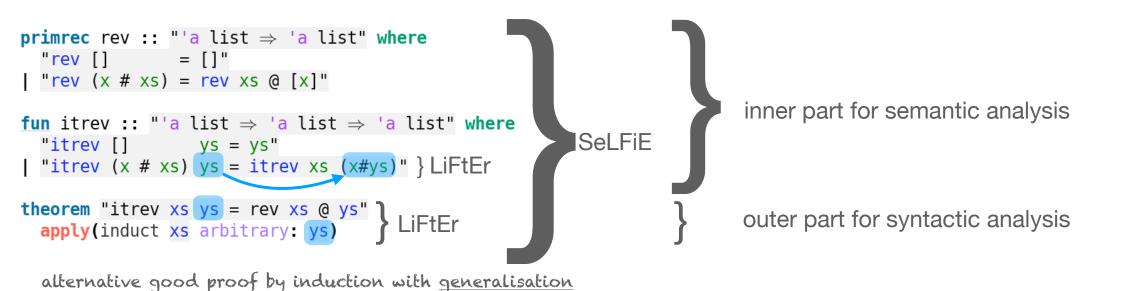
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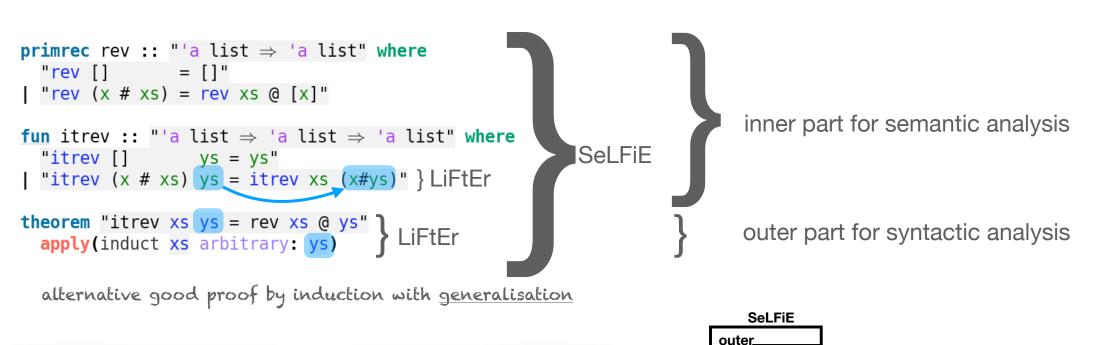
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"Isabelle/HOL A Proof Assistant for Higher-Order Logic" Tobias Nipkow, Lawrence C. Paulson, Markus Wenzel page 36 outer part for syntactic analysis



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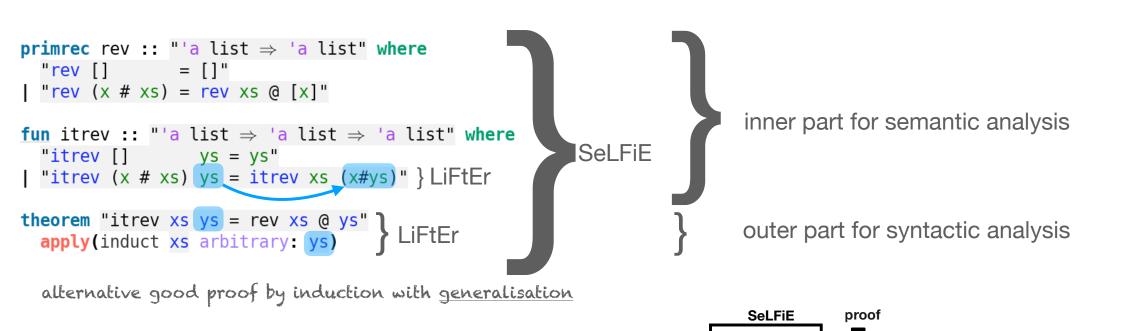
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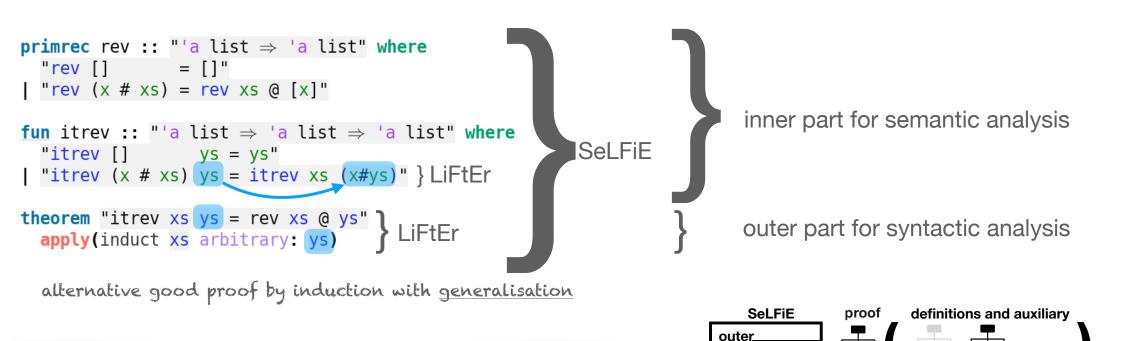


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inner

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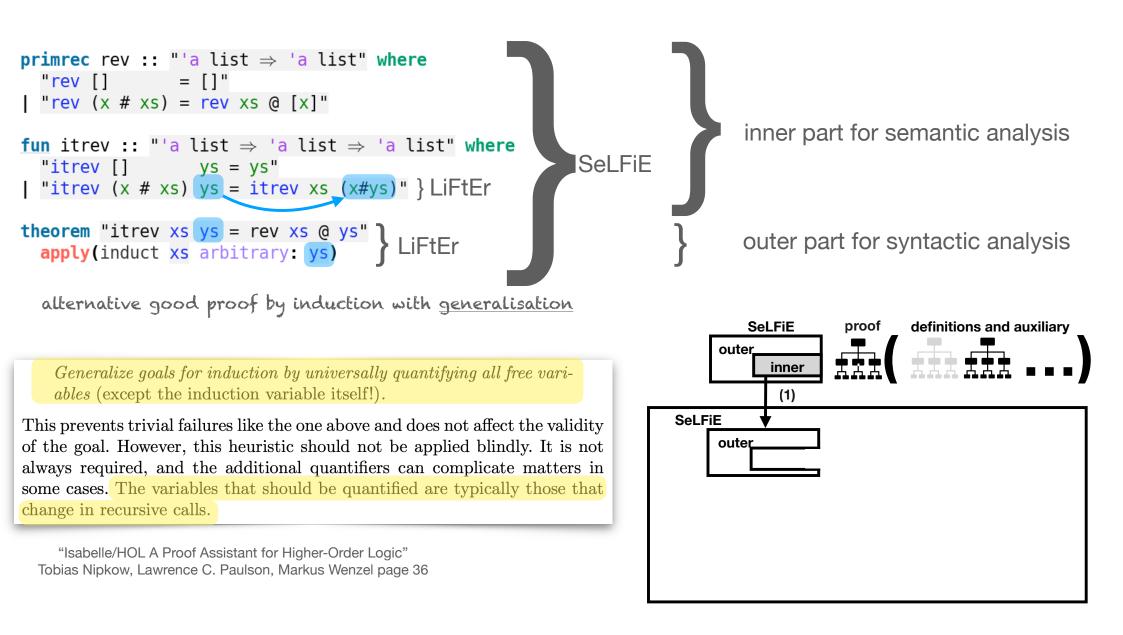
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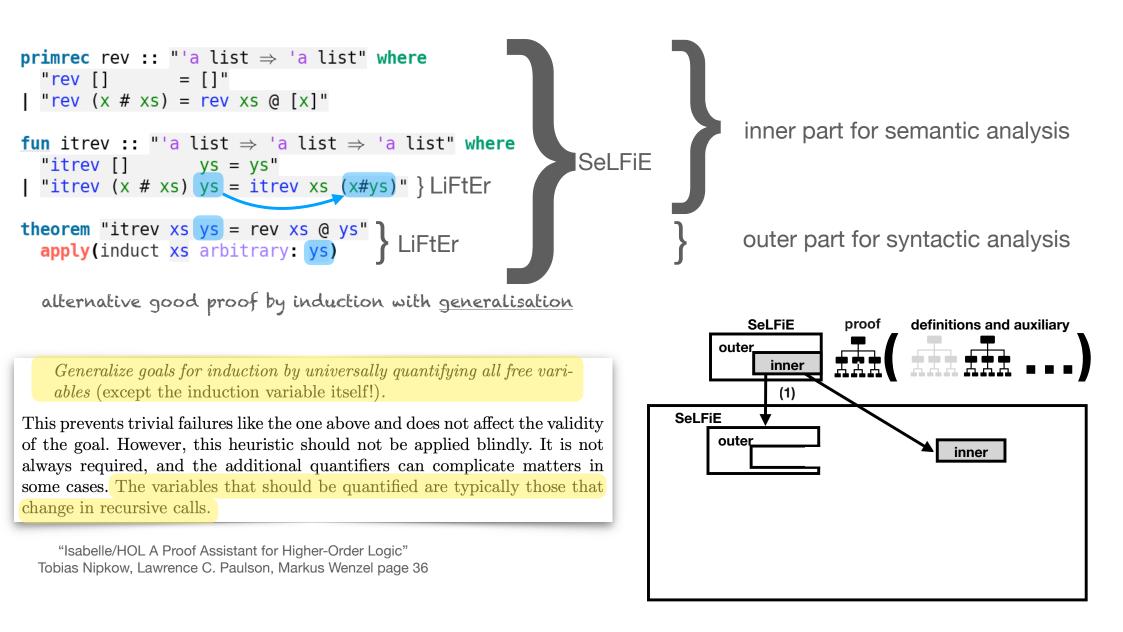


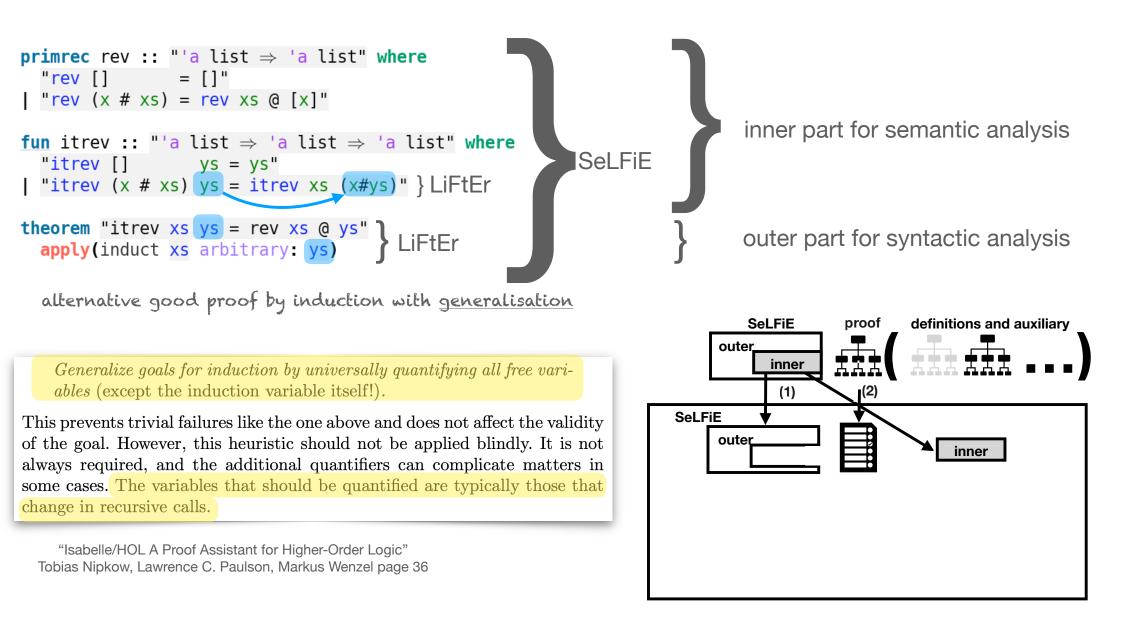
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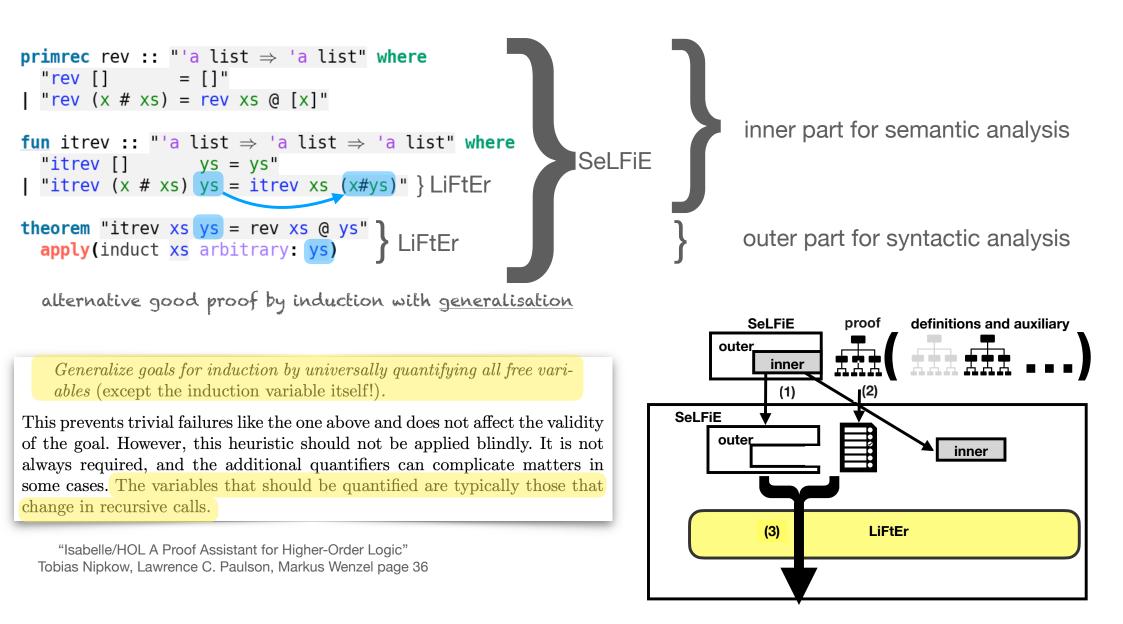
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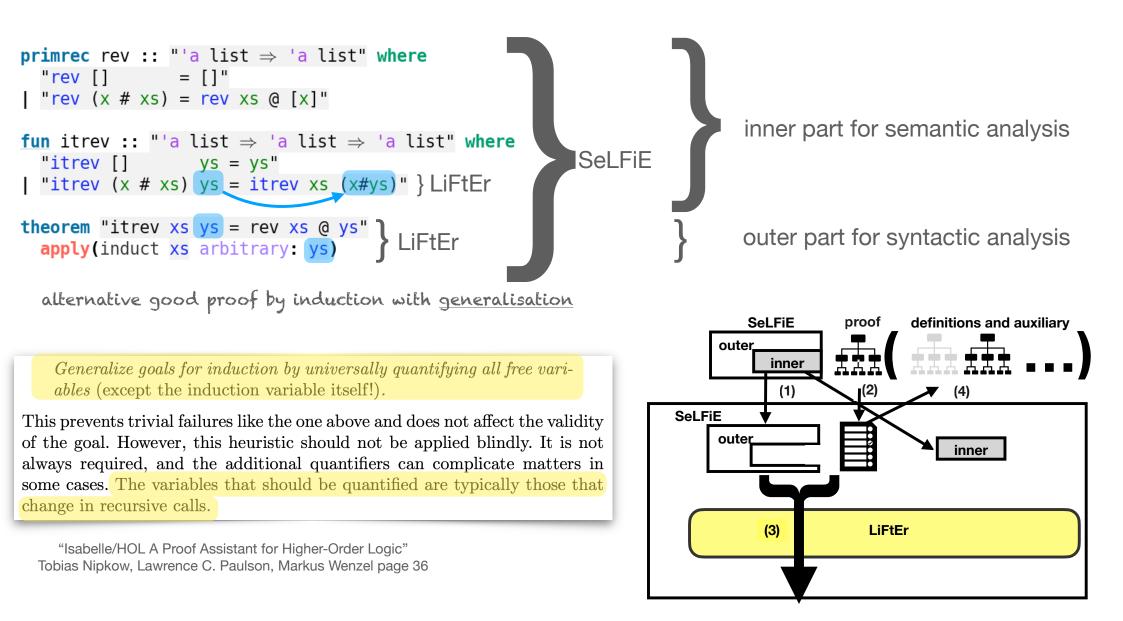
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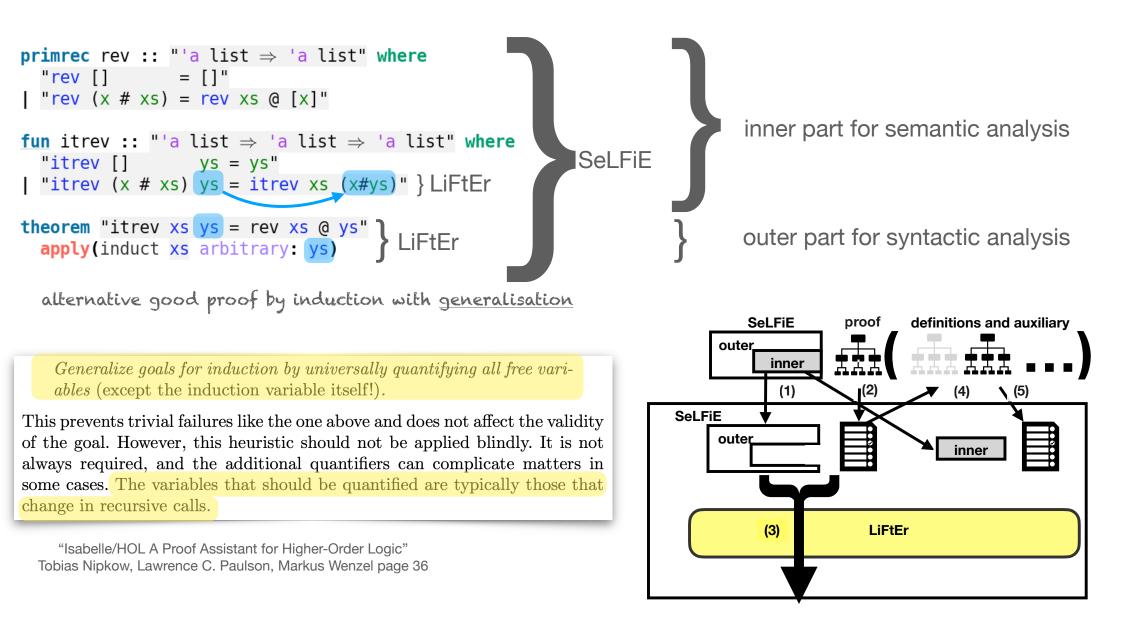


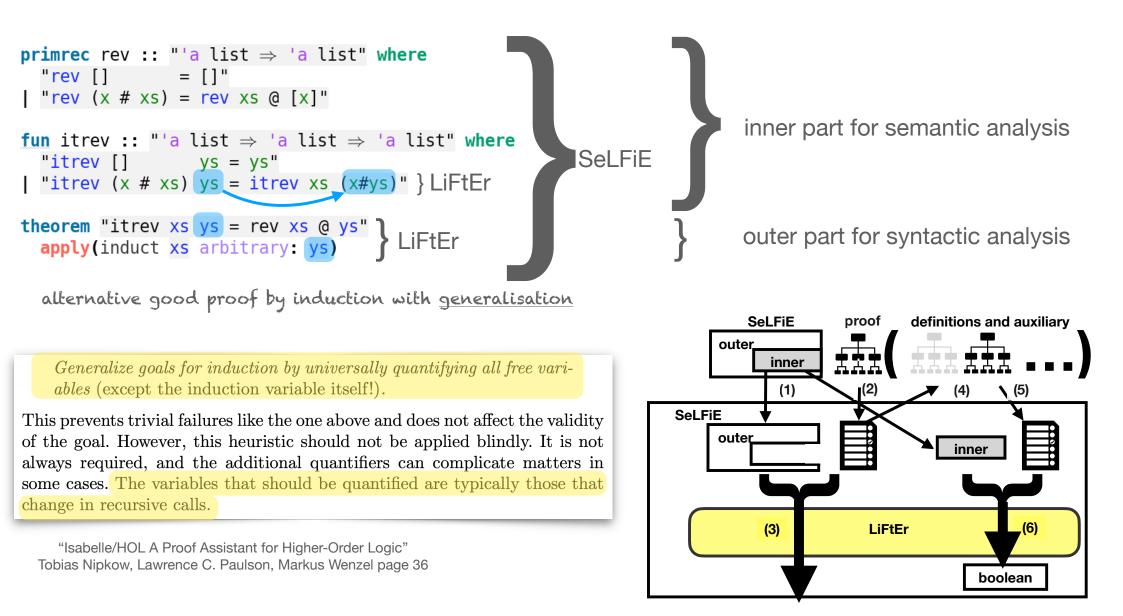


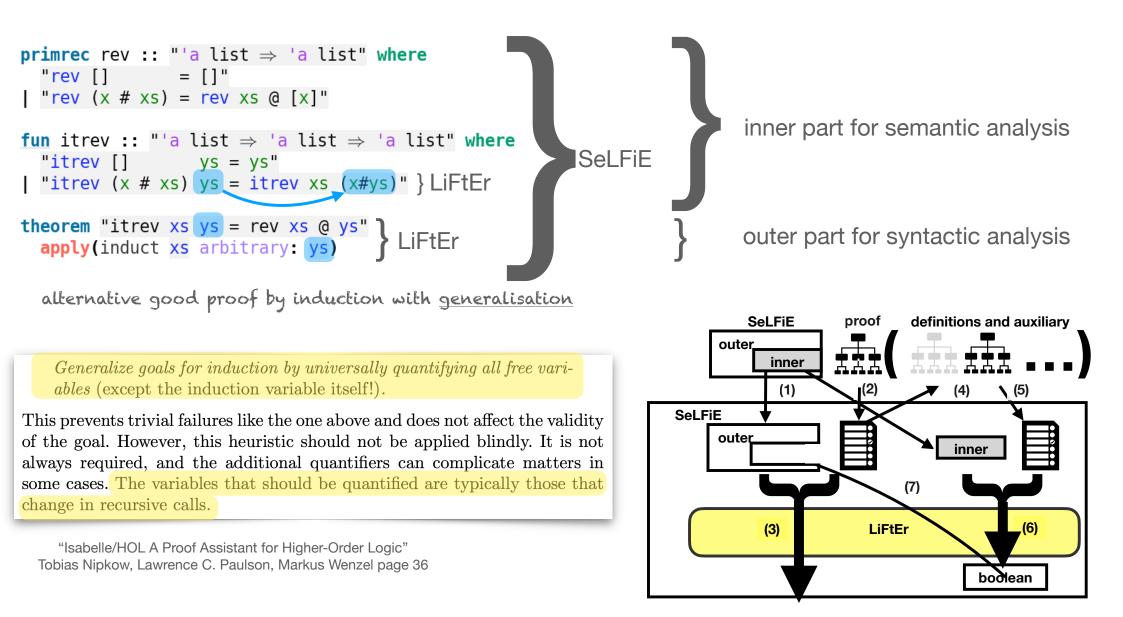


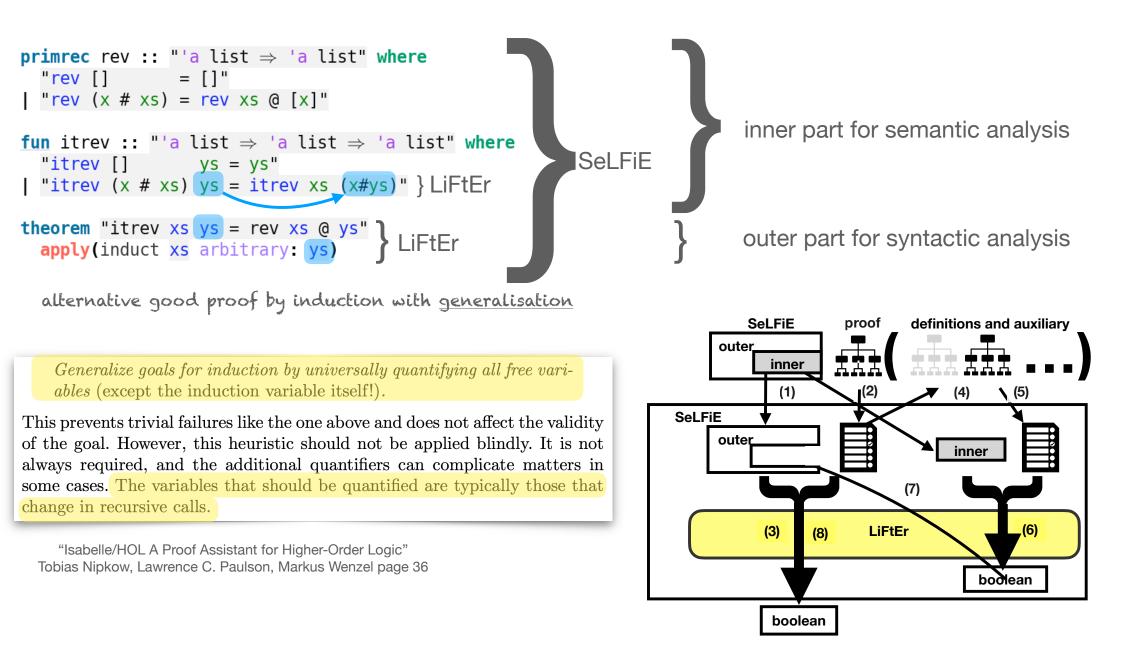


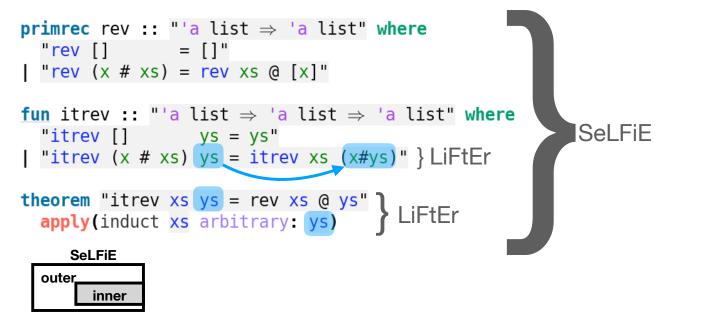


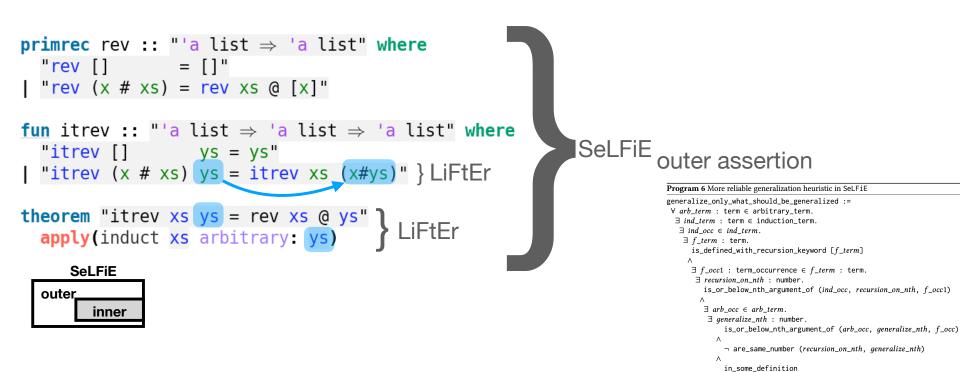




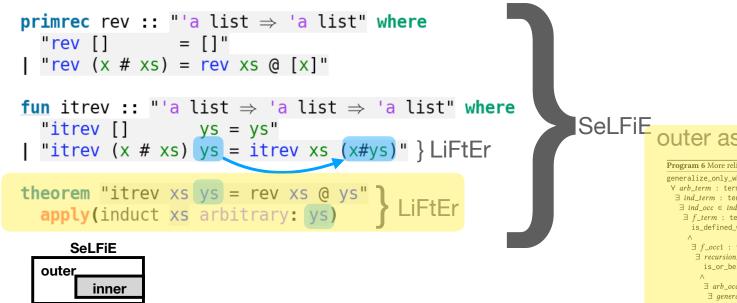






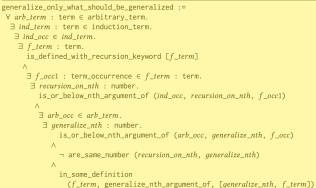


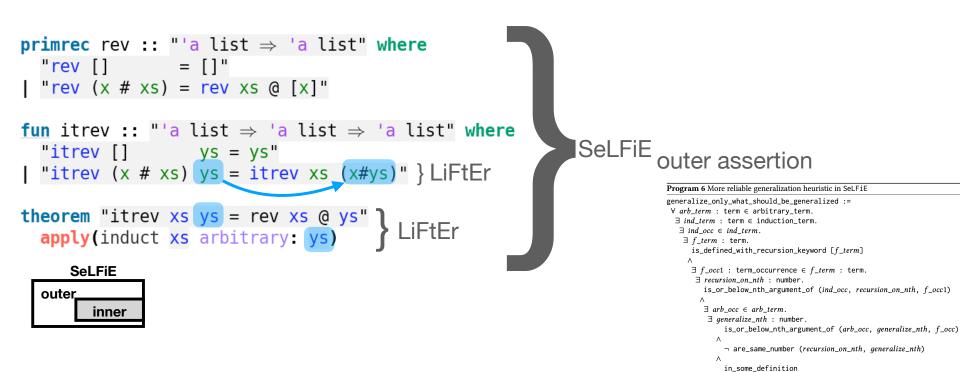
(f_term, generalize_nth_argument_of, [generalize_nth, f_term])



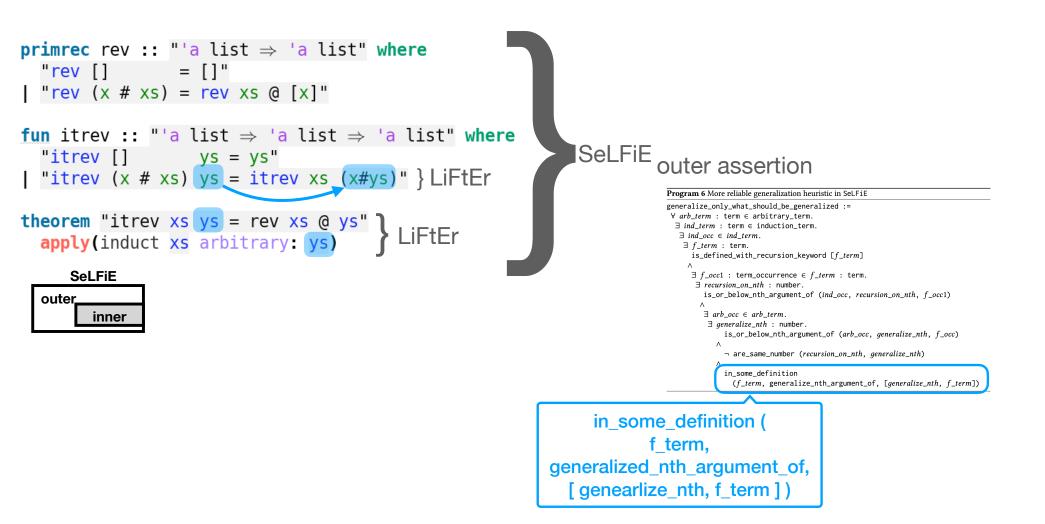
outer assertion

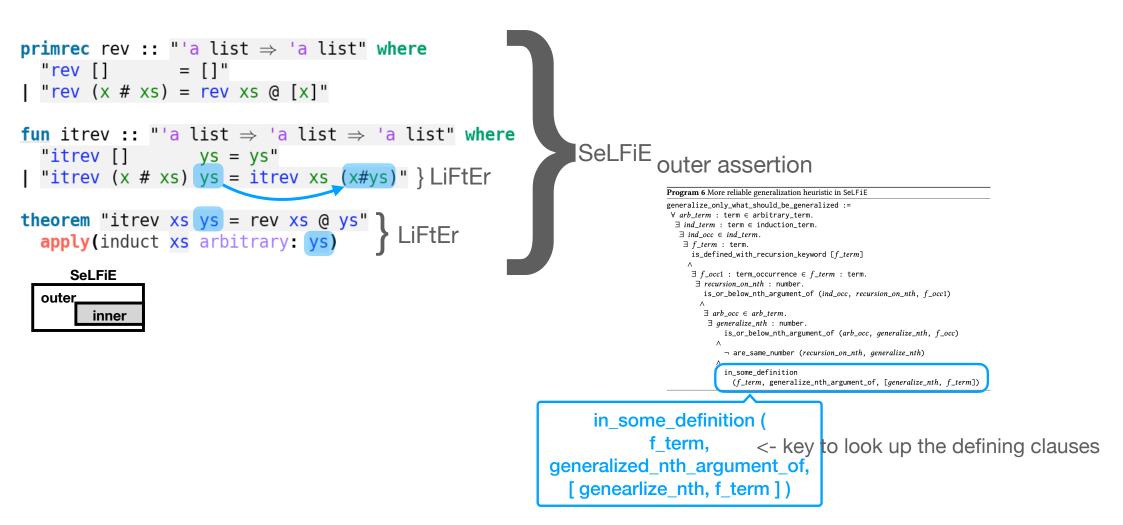
Program 6 More reliable generalization heuristic in SeLFiE

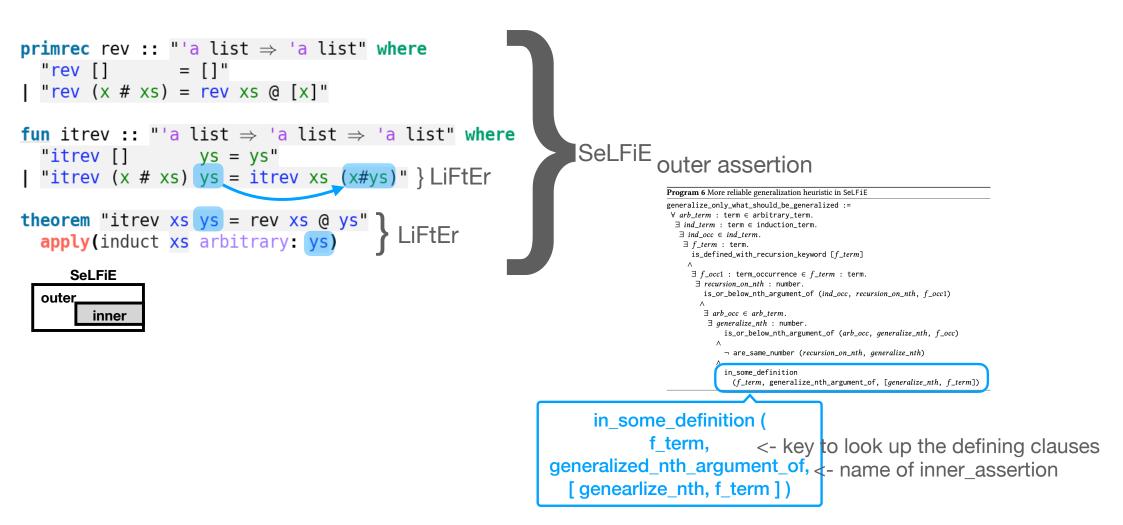


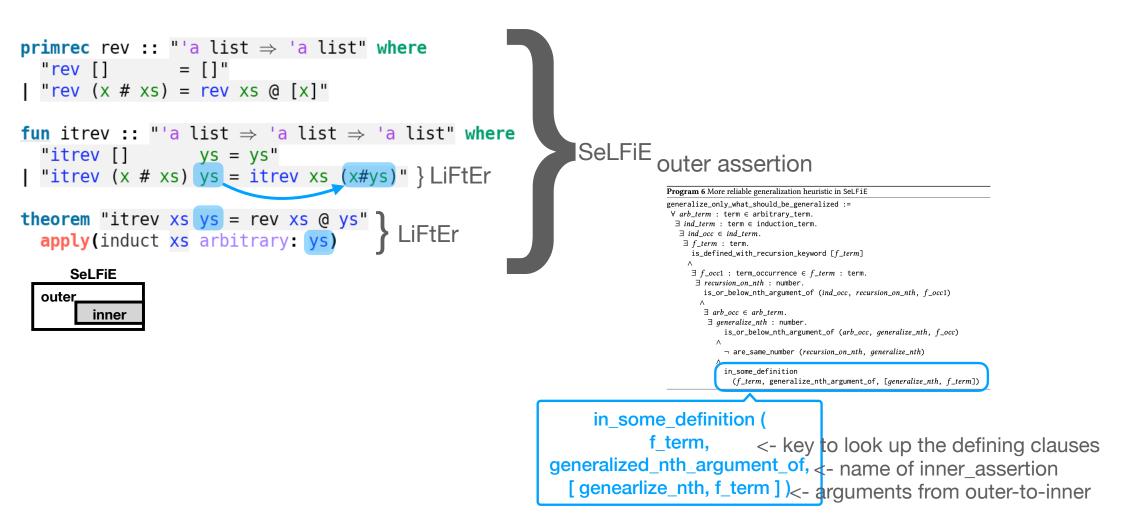


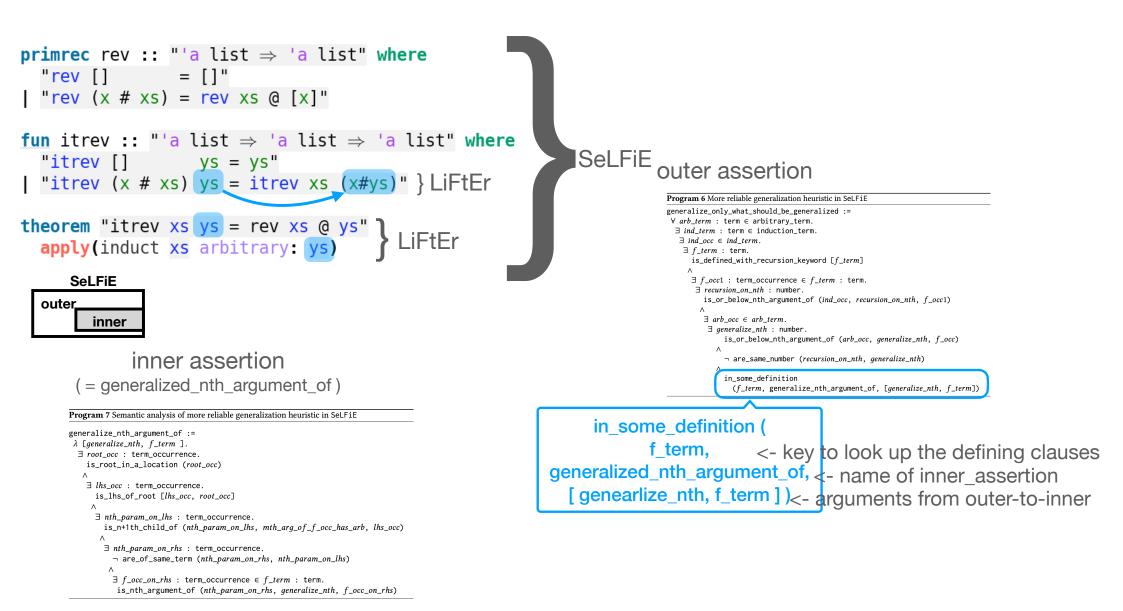
(f_term, generalize_nth_argument_of, [generalize_nth, f_term])

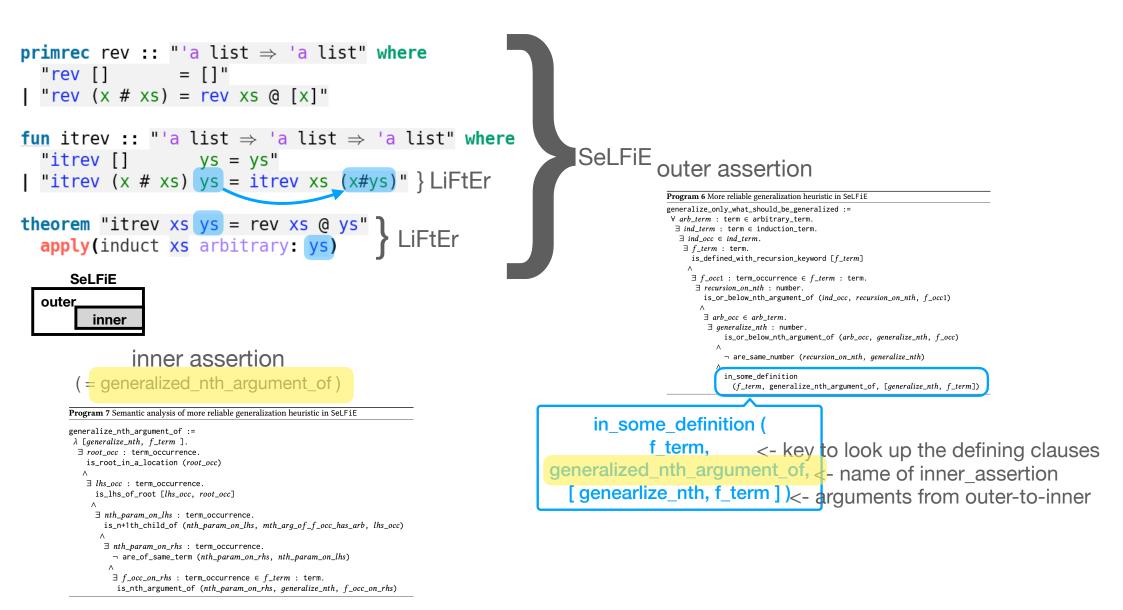


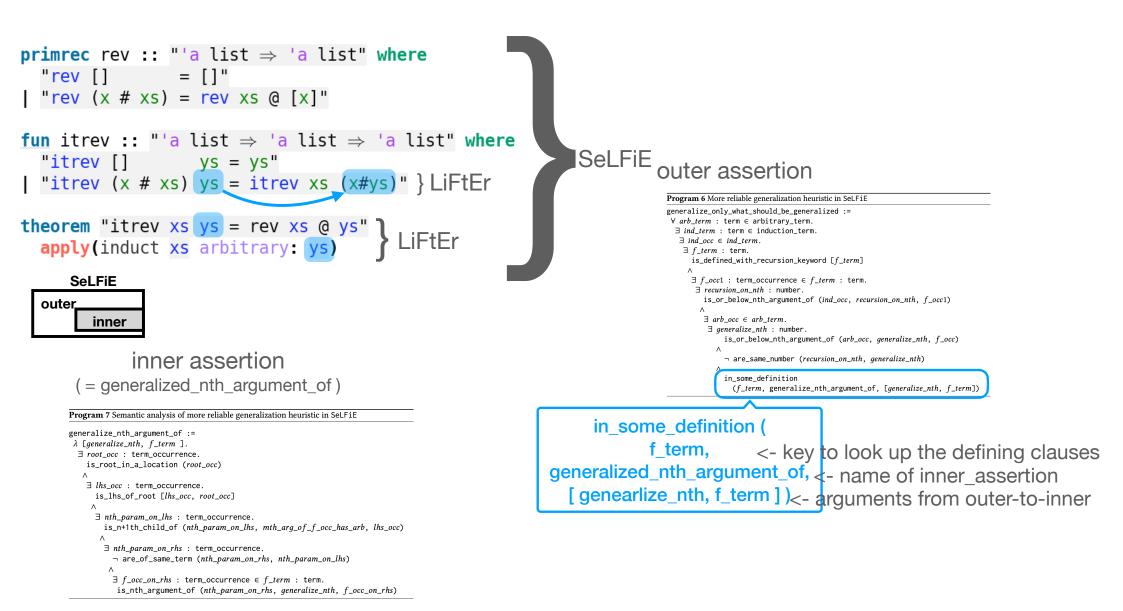


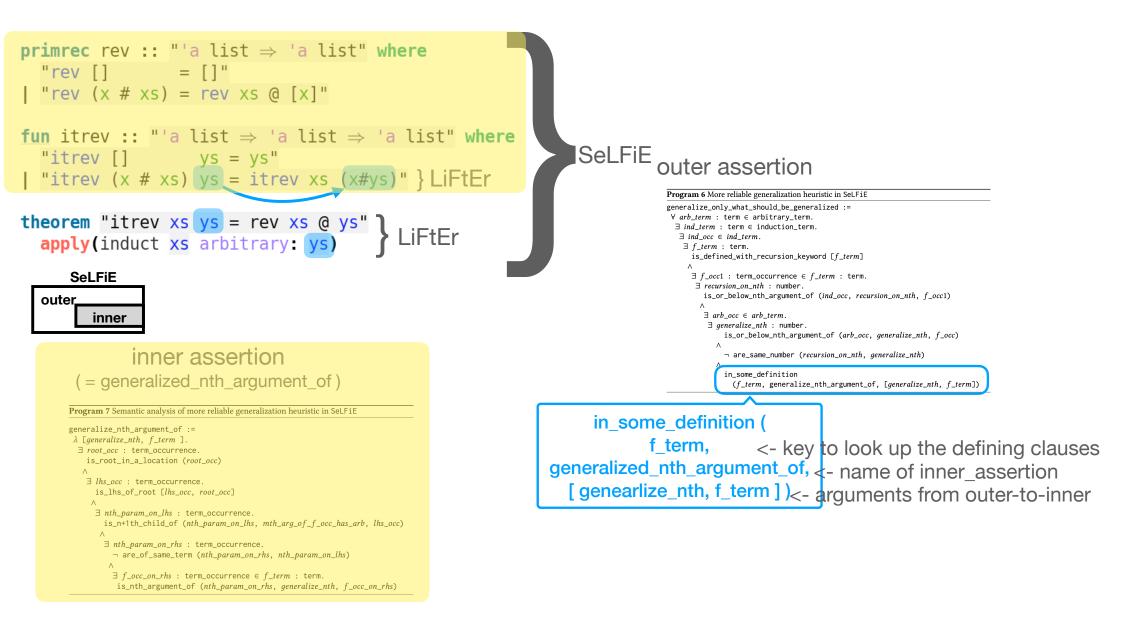


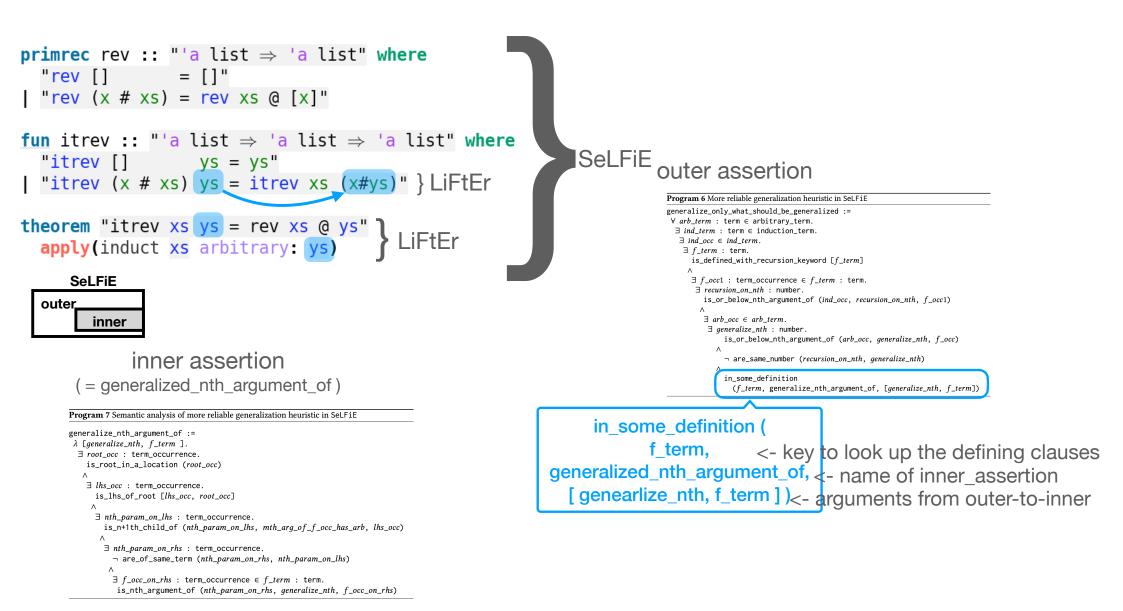


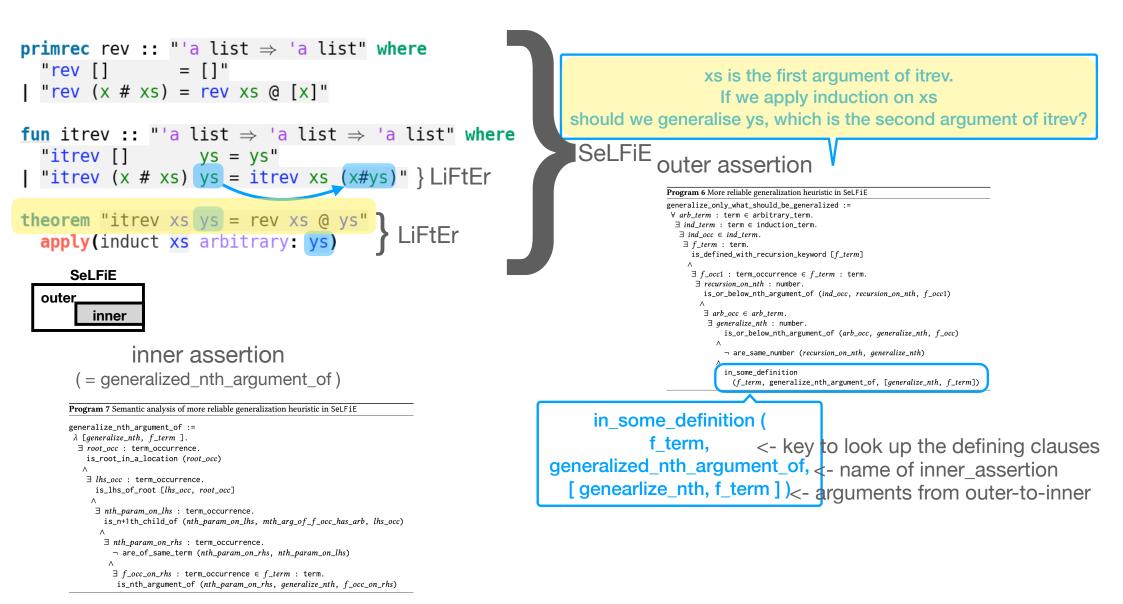


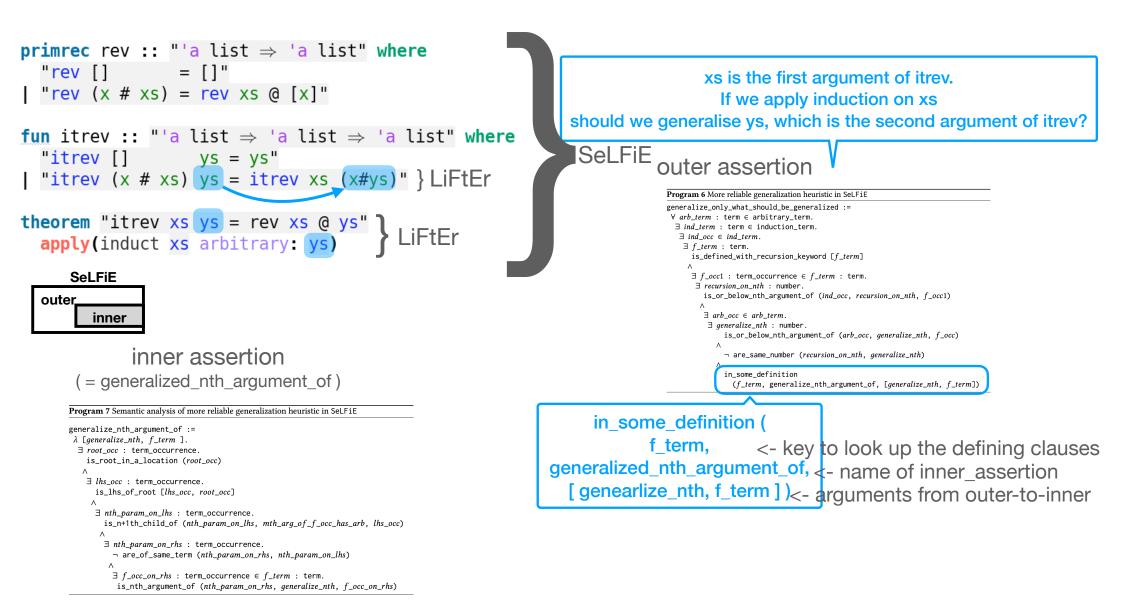


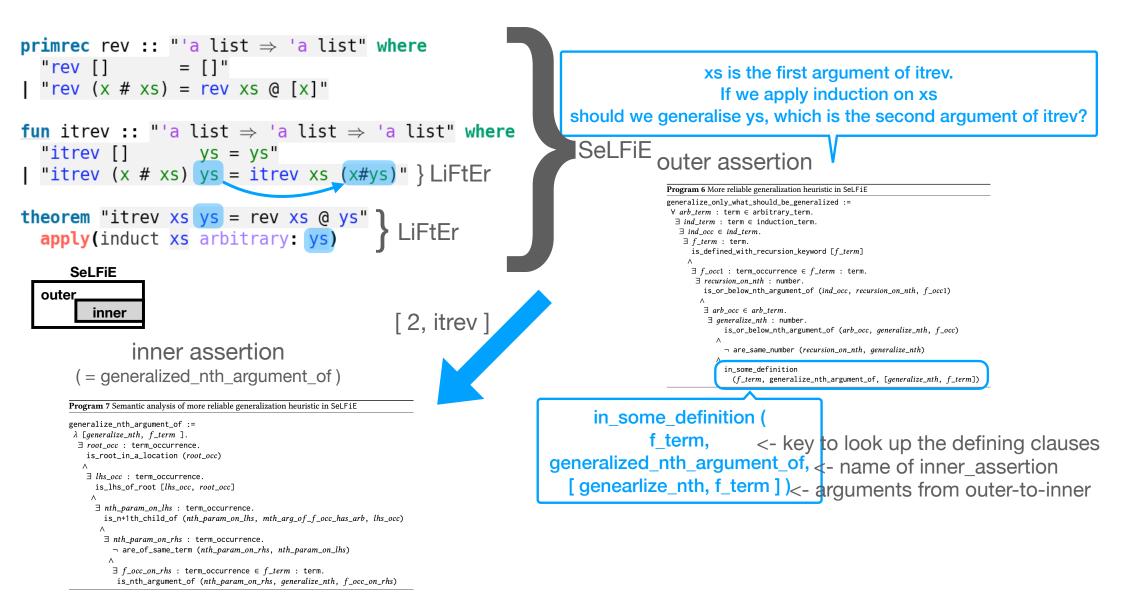


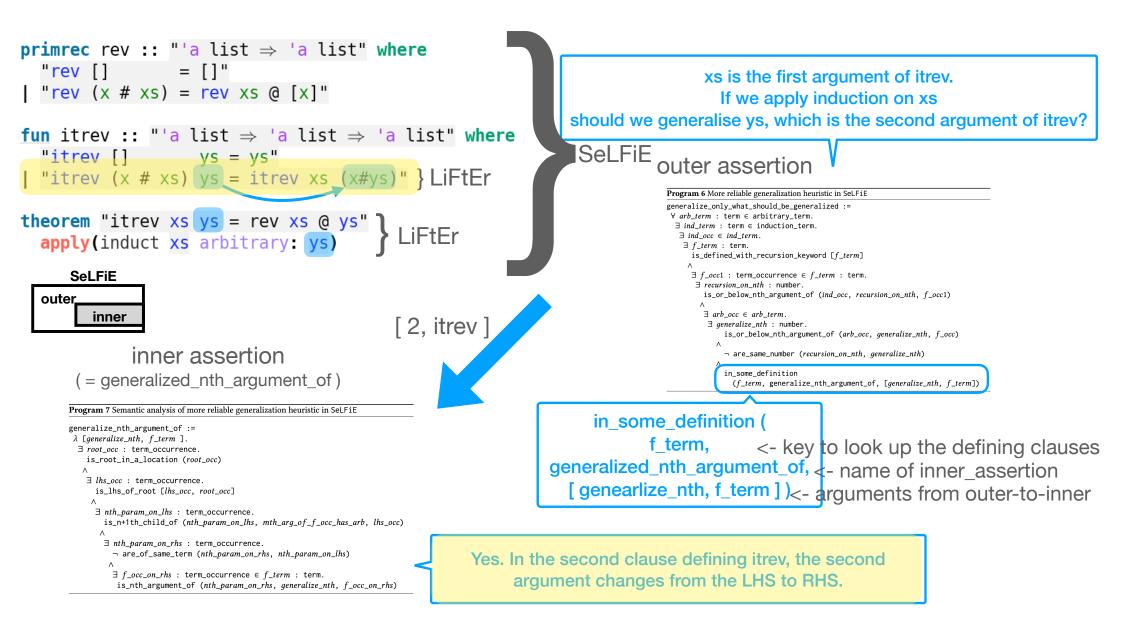


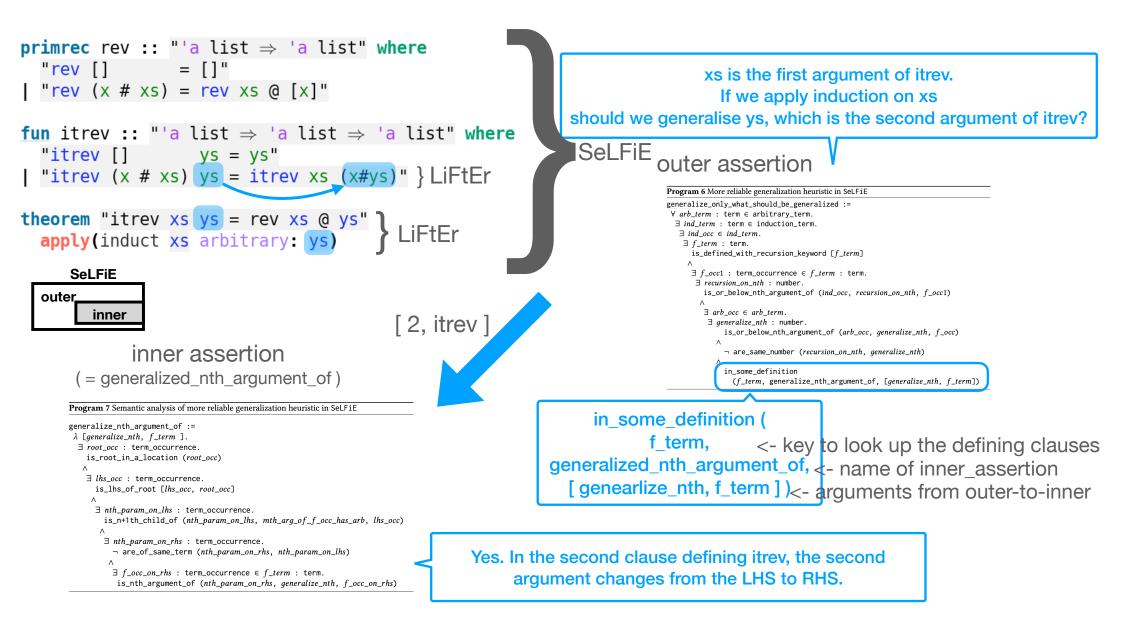


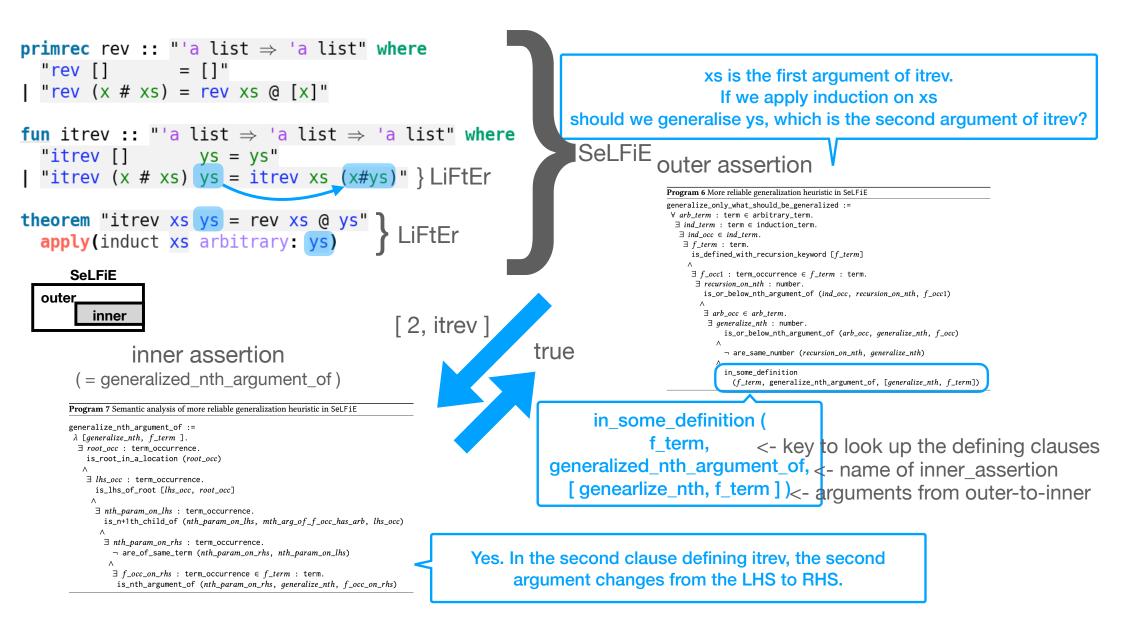










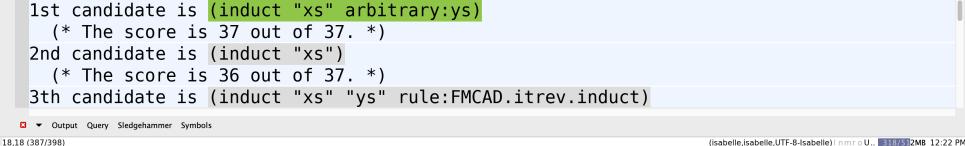


DEMO

semantic_induct

The example theorem is taken from "Isabelle/HOL A Proof Assistant for Higher-Order Logic" Tobias Nipkow, Lawrence C. Paulson, Markus Wenzel page 36

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  FMCAD.thy (~/Workplace/PSL_Perform/PSL/Example/)
•
  theory FMCAD
  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
File Browser Documentation
  <sub>3</sub>begin
   primrec rev :: "'a list \Rightarrow 'a list" where
     "rev [] = []"
  _{7} [ "rev (x # xs) = rev xs @ [x]"
  value "rev [1::nat, 2, 3]"
 fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] ys = ys"
  12
  |_{13} | "itrev (x # xs) ys = itrev xs (x#ys)"
  use "itrev [1::nat, 2, 3] []"
 h<sub>17</sub> theorem "itrev xs ys = rev xs @ ys"
    semantic induct
                                                               ✓ Proof state ✓ Auto update Update Sear...
```



Sidekick

State

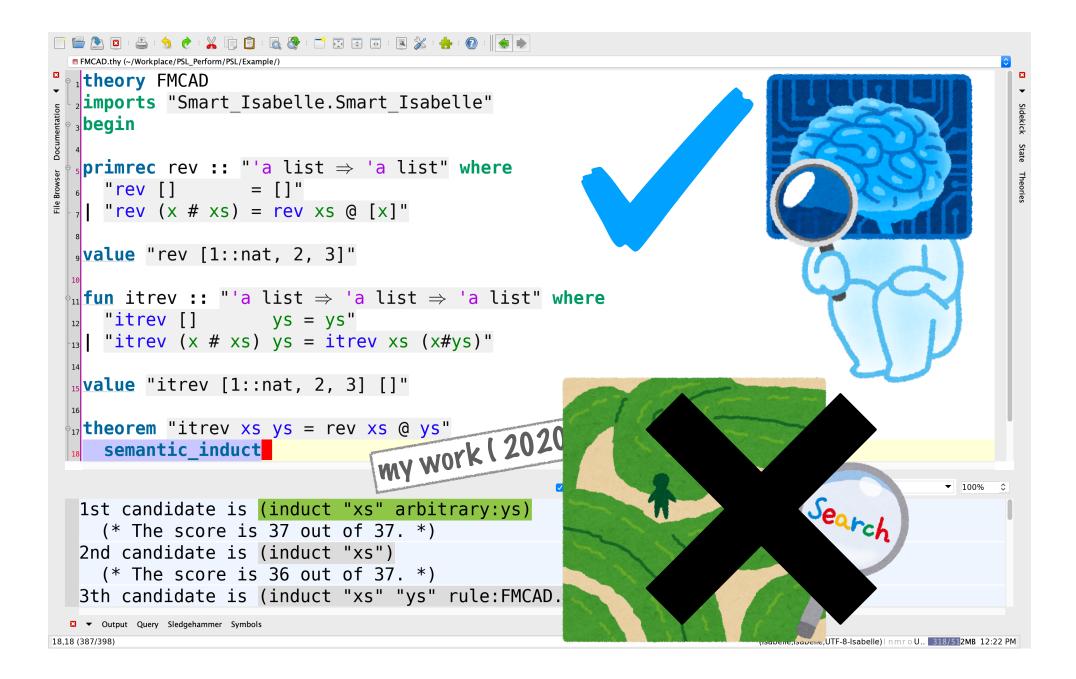
Theories

▼ 100%

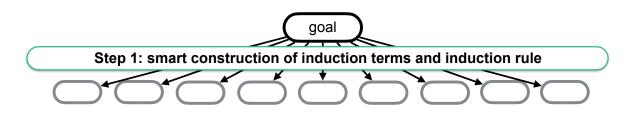
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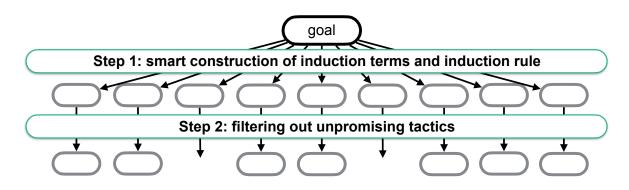
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  FMCAD.thy (~/Workplace/PSL_Perform/PSL/Example/)
                                                                                                                       •
  theory FMCAD
  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
                                                                                                                       Sidekick
File Browser Documentation
  <sub>3</sub>begin
                                                                                                                       State
   primrec rev :: "'a list \Rightarrow 'a list" where
                                                                                                                       Theories
     "rev [] = []"
  _{7} [ "rev (x # xs) = rev xs @ [x]"
  value "rev [1::nat, 2, 3]"
 fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] vs = vs"
  12
  |_{13} | "itrev (x # xs) ys = itrev xs (x#ys)"
  use "itrev [1::nat, 2, 3] []"
                                      my work ( 2020 )
 hear "itrev xs ys = rev xs @ ys"
      semantic induct
                                                              ✓ Proof state ✓ Auto update Update Sear...
                                                                                                             ▼ 100%
                                                                                                                    0
   1st candidate is (induct "xs" arbitrary:ys)
     (* The score is 37 out of 37. *)
   2nd candidate is (induct "xs")
      (* The score is 36 out of 37. *)
   3th candidate is (induct "xs" "ys" rule:FMCAD.itrev.induct)
  Output Query Sledgehammer Symbols
18,18 (387/398)
                                                                                       (isabelle,isabelle,UTF-8-Isabelle) | nmroU. 318/512MB 12:22 PM
```

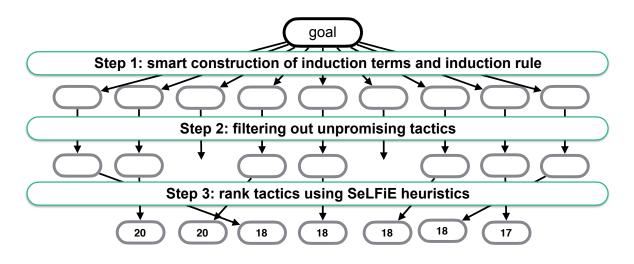
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  FMCAD.thy (~/Workplace/PSL_Perform/PSL/Example/)
                                                                                                                      •
  1 theory FMCAD
  <sup>2</sup>imports "Smart Isabelle.Smart Isabelle"
                                                                                                                      Sidekick
File Browser Documentation
  <sub>3</sub>begin
                                                                                                                      State
   primrec rev :: "'a list \Rightarrow 'a list" where
                                                                                                                      Theories
    "rev [] = []"
  "rev (x # xs) = rev xs @ [x]"
  value "rev [1::nat, 2, 3]"
 \phi_{11} fun itrev :: "'a list \Rightarrow 'a list \Rightarrow 'a list" where
     "itrev [] ys = ys"
  12
  |_{13} | "itrev (x # xs) ys = itrev xs (x#ys)"
  value "itrev [1::nat, 2, 3] []"
                                      my work (2020
 here witrev xs ys = rev xs @ ys"
      semantic induct
                                                                                                             ▼ 100%
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   1st candidate is (induct "xs" arbitrary:ys)
     (* The score is 37 out of 37. *)
   2nd candidate is (induct "xs")
     (* The score is 36 out of 37. *)
   3th candidate is (induct "xs" "ys" rule:FMCAD.
  Output Query Sledgehammer Symbols
18,18 (387/398)
                                                                                          e, Isabene, UTF-8-Isabelle) | nmr o U., 318/512MB 12:22 PM
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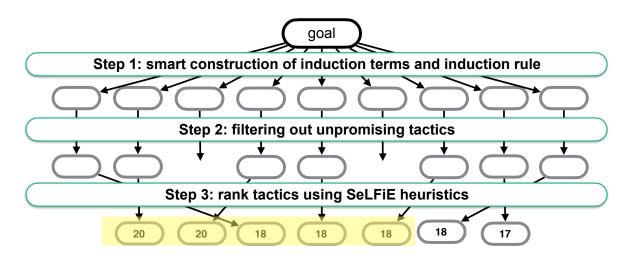


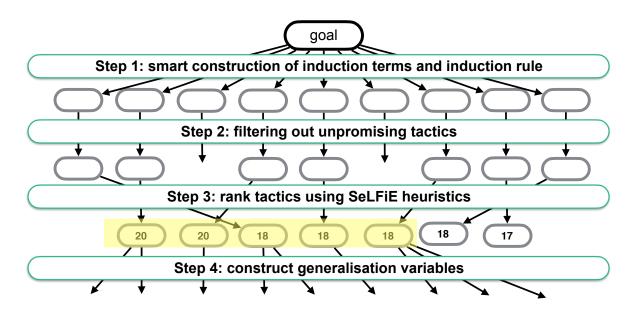


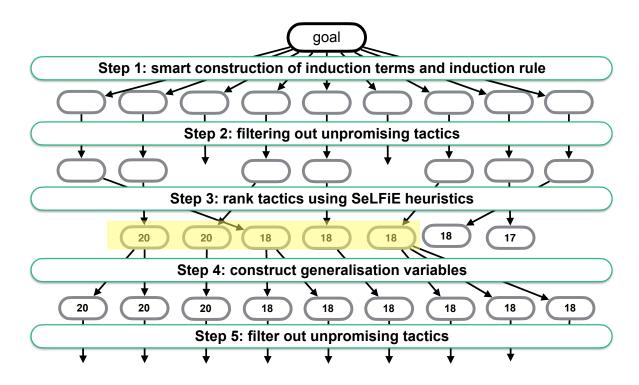


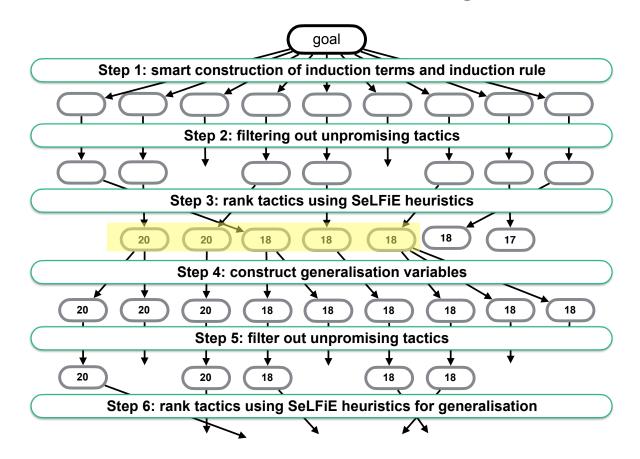


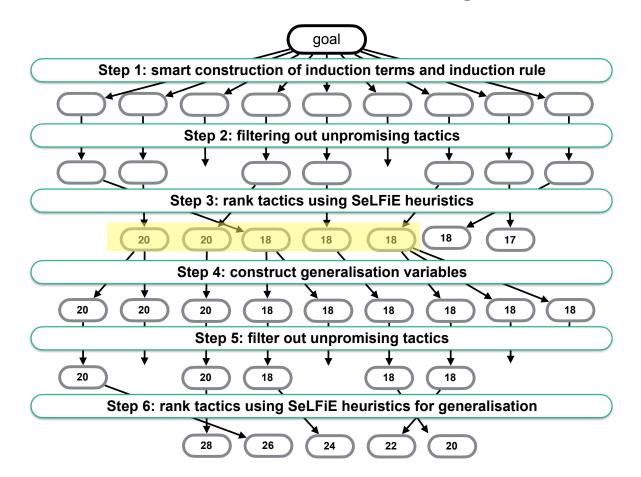


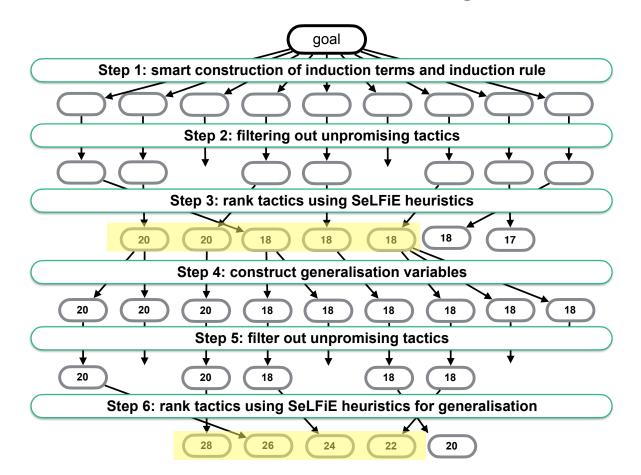


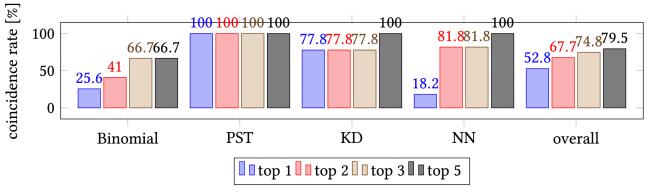






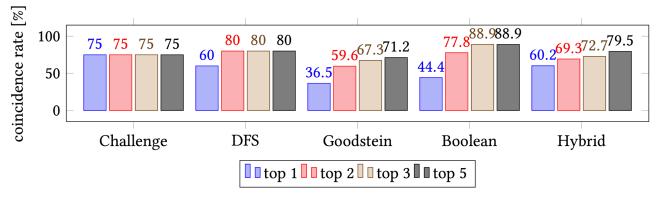




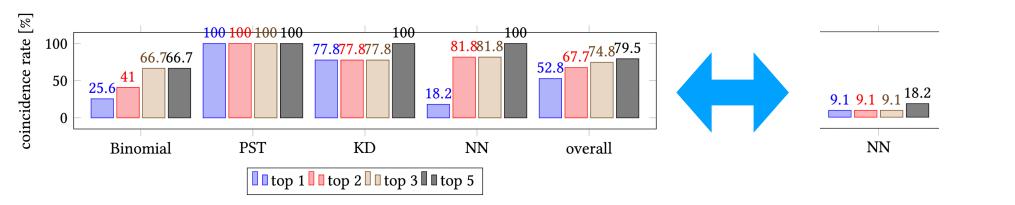


recommendation using SeLFiE

(b) Coincidence rates of semantic_induct for each theory file (part 1).



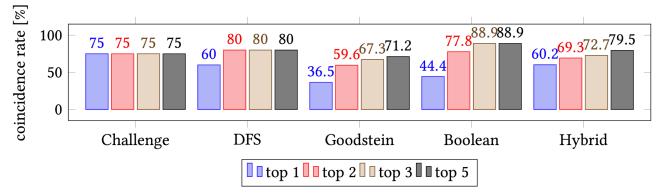
(d) Coincidence rates of semantic_induct for each theory file (part 2).



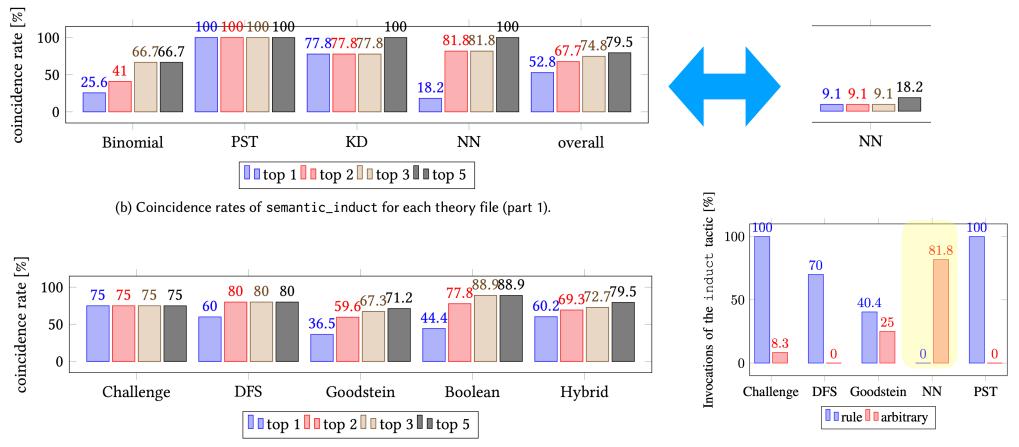
recommendation using LiFtEr

recommendation using SeLFiE

(b) Coincidence rates of semantic_induct for each theory file (part 1).



(d) Coincidence rates of semantic_induct for each theory file (part 2).



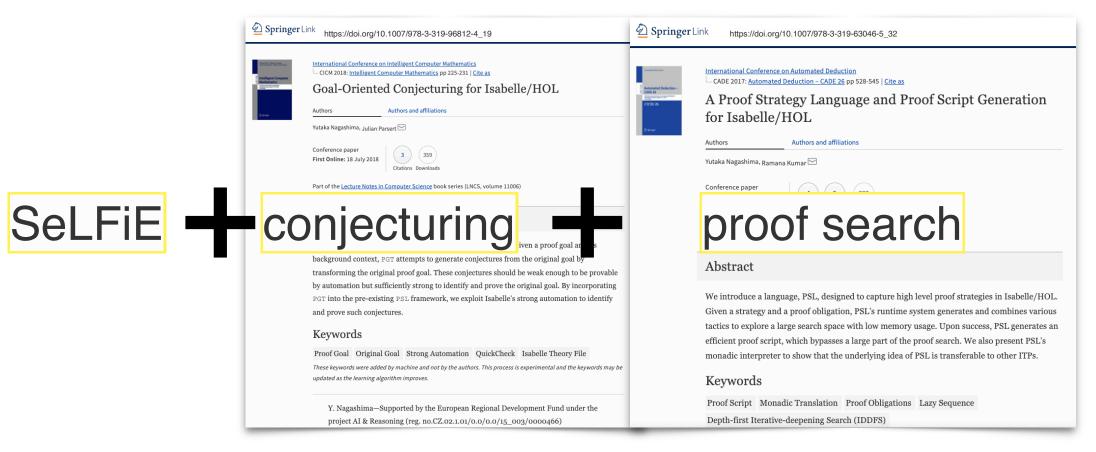
recommendation using LiFtEr

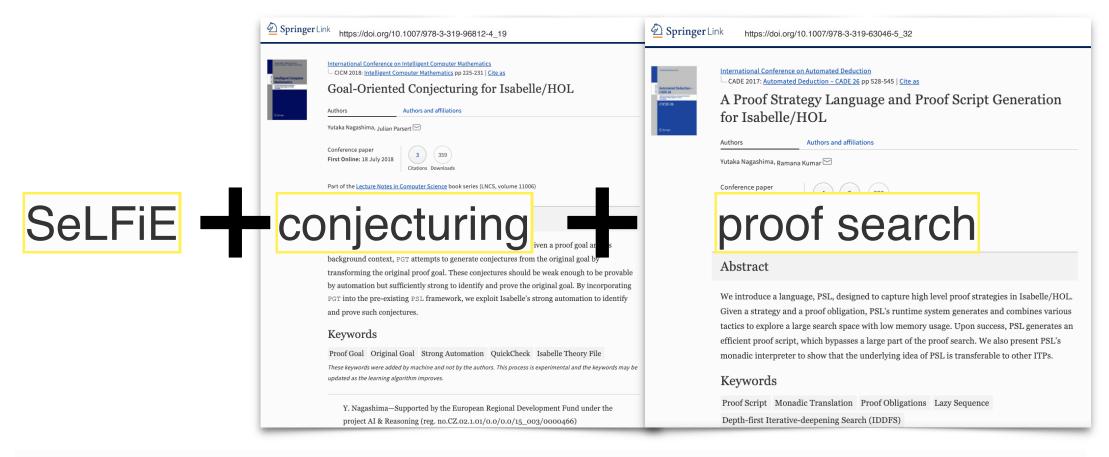
recommendation using SeLFiE

⁽d) Coincidence rates of semantic_induct for each theory file (part 2).









==> fully automatic inductive prover in Isabelle/HOL

Future work THA Depringer Link Der Springer Link https://doi.org/10.1007/978-3-319-96812-4 19 https://doi.org/10.1007/978-3-319-63046-5 32 International Conference on Intelligent Computer Mathematics International Conference on Automated Deduction CICM 2018: Intelligent Computer Mathematics pp 225-231 | Cite as CADE 2017: Automated Deduction - CADE 26 pp 528-545 | Cite as Goal-Oriented Conjecturing for Isabelle/HOL A Proof Strategy Language and Proof Script Generation Authors and affiliations Authors for Isabelle/HOL Yutaka Nagashima, Julian Parsert 🖂 Authors Authors and affiliations Conference paper 3 359 First Online: 18 July 2018 Yutaka Nagashima, Ramana Kumar 🖂 Citations Download Part of the Lecture Notes in Computer Science book series (LNCS, volume 11006) Conference paper proof search SeLFil background context, PGT attempts to generate conjectures from the original goal Abstract transforming the original proof goal. These conjectures should be weak enough to be provable by automation but sufficiently strong to identify and prove the original goal. By incorporating We introduce a language, PSL, designed to capture high level proof strategies in Isabelle/HOL. PGT into the pre-existing PSL framework, we exploit Isabelle's strong automation to identify Given a strategy and a proof obligation, PSL's runtime system generates and combines various and prove such conjectures. tactics to explore a large search space with low memory usage. Upon success, PSL generates an Keywords efficient proof script, which bypasses a large part of the proof search. We also present PSL's Proof Goal Original Goal Strong Automation QuickCheck Isabelle Theory File monadic interpreter to show that the underlying idea of PSL is transferable to other ITPs. These keywords were added by machine and not by the authors. This process is experimental and the keywords may be updated as the learning algorithm improves Keywords Proof Script Monadic Translation Proof Obligations Lazy Sequence Y. Nagashima-Supported by the European Regional Development Fund under the Depth-first Iterative-deepening Search (IDDFS) project AI & Reasoning (reg. no.CZ.02.1.01/0.0/0.0/15_003/0000466)

==> fully automatic inductive prover in Isabelle/HOL